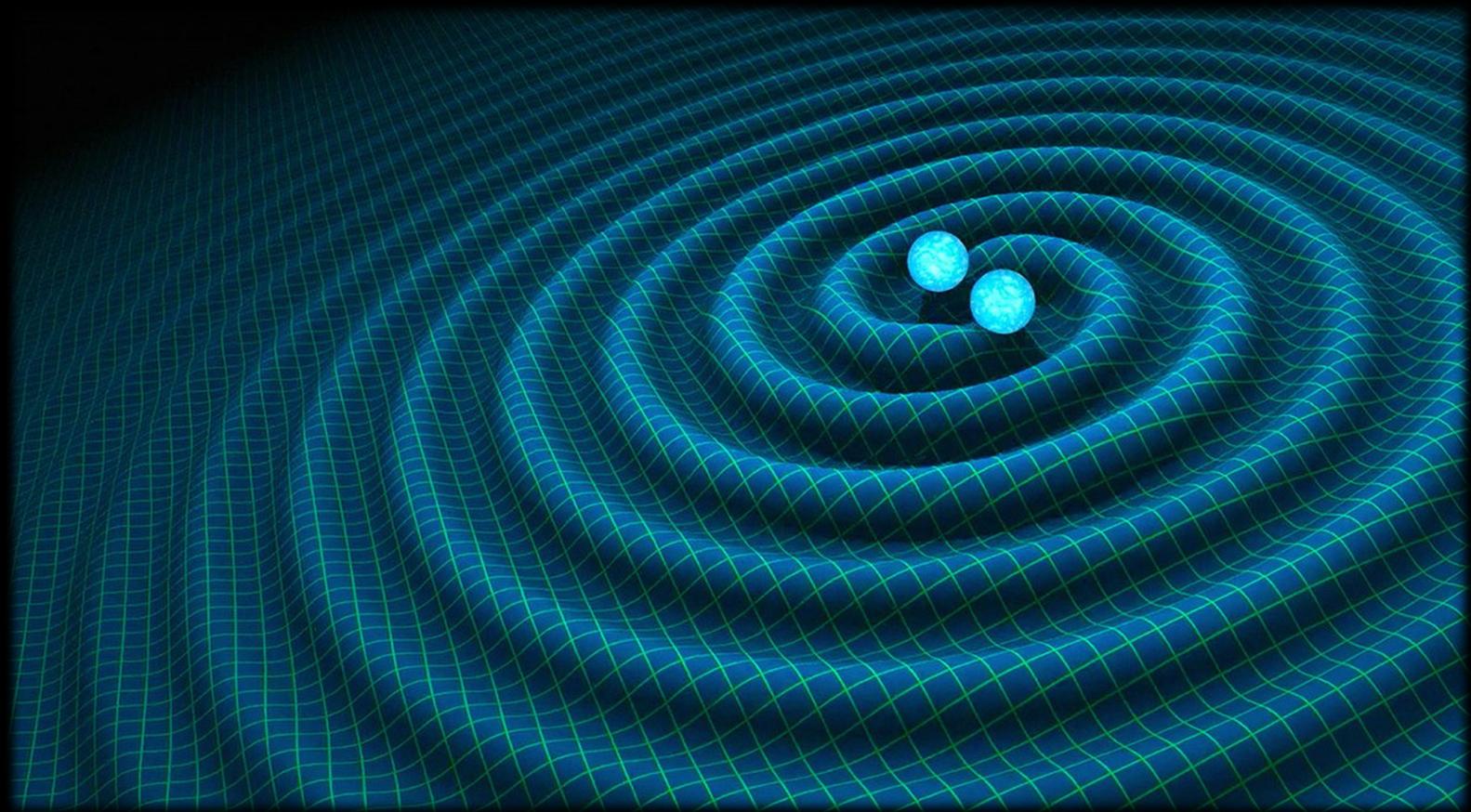


General Relativity



1 - Introduction

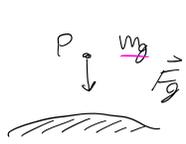
General Relativity is not a Quantum Theory

Useful Notations

1. **Event**: A physics occurrence at some point in space and time
2. **Observer**: A reference frame
N.P.: we can switch observer through coordinate transformations.
3. **Local time**: Each observer is equipped with an ideal standard clock and he can assign a temporal order to events
→ He can tell if an event comes early than others
4. **Worldline**: The path that an object follows in spacetime

The Equivalence Principle

1. Galilean Version



$$1. \vec{F}_g = -m_g \vec{\nabla} \phi$$

↳ gravitational mass

$$2. \vec{F} = m_i \vec{a}$$

↳ inertial mass

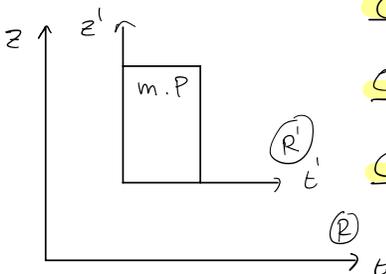
~ Tells how much an object resist to SOMETHING

The 2 equations are FUNDAMENTALLY DIFFERENT OBJECTS

Empirically $m_i = m_g$ ~ Some experiments did that

CONSEQUENCE \Rightarrow Universally Free-Fall (all the objects fall at the same speed)

2. Einstein Version



Case 0: Elevator in outer space free of all forces
→ P floats

Case 1: Elevator in outer space uniformly accelerated
→ P moves towards bottom

Case 2: Elevator gets closer to Earth

→ P moves towards bottom

Einstein Principle

You cannot distinguish between this 2 objects

→ Gravity does not depend on the mass

Solving case 1:

$$\Delta(\Delta) = \frac{1}{2} g t^2 \Rightarrow \dot{\Delta}(t) = g \quad \text{and} \quad z' = z - \frac{1}{2} g t^2$$

$$t' = t \quad (\text{ignore relativistic effects})$$

In R: $F = m\ddot{z}$

In R': $F' = m\ddot{z}' = m\ddot{z} - mg \Rightarrow F' = F - mg$ → The acceleration of R' respect R looks like gravitational force in R'

Case 3: Elevator in the Earth Field and cut the rope
 → P Floats is equal to 0

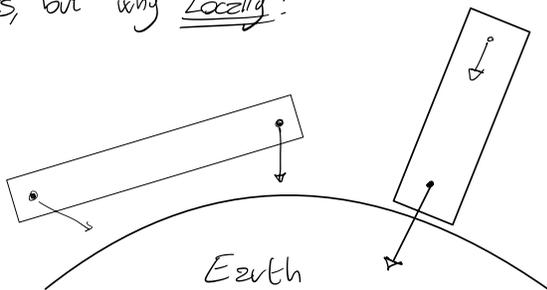
So this explain Einstein Principle:

"No physics experiment can distinguish locally between a uniform grav. field acting on the local inertial observer and a uniform acceleration which respect to that local inertial observer. The local inertial observer is the one for which SR holds"



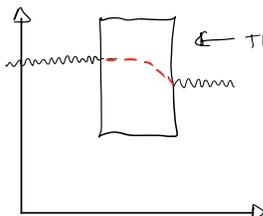
A falling object drops exactly the same on a planet or in an accelerating frame of reference

Yes, but why locally?



The gravitational field change in space, everything must be done locally

Light Discussion



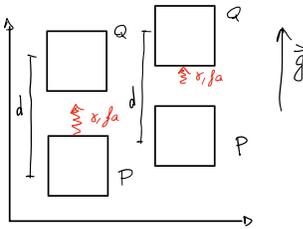
← The elevator move!

In an accelerated reference frame Light bend on the action by a gravitational field

- light exit a little bit lower

→ Light Bends

Gravitational Redshift



- Photon's Time of Flight $\Delta t = \frac{d}{c}$
- Velocity increase for P, Q
 $\Delta v = g \Delta t \Rightarrow \Delta v = \frac{gd}{c}$

- Doppler shift:

$$\frac{f_a}{f_p} = 1 - \frac{\Delta v}{c} = 1 - \frac{gd}{c^2}$$

Because of the equivalence principle

2 - Special Relativity

1. EVENTS: (single point)

(x^0, x^1, x^2, x^3) where $x^0 = ct$
 $\{x^i\}_{i=1,2,3} =$ position space \vec{x}

This is how we label events on Minkowski Space-Time

2. DISTANCE:

$$ds^2 = (x^0)^2 - \sum_{\mu} (x^{\mu})^2 \quad \text{LINE ELEMENT}$$

Alternative conventions: $ds^2 = -(x^0)^2 + \sum_{\mu} (x^{\mu})^2$

3. MATRIX TENSOR

$$\eta_{\mu\nu} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \bullet \text{ it's invariant}$$

Using that the "LINE ELEMENT" is: $ds^2 = \sum_{\mu, \nu} \eta_{\mu\nu} dx^{\mu} dx^{\nu}$

4. EINSTEIN SUMMATION CONVENTION

Repeated indices are summed $\Rightarrow ds^2 = \eta_{\mu\nu} dx^{\mu} dx^{\nu}$

5. LORENTZ TRANSFORMATION

Transformation $\begin{cases} \text{LINEAR TRANSFORMATIONS} \\ \text{Leave } ds^2 \text{ INVARIANT} \end{cases} \rightarrow x^{\mu} \rightarrow x'^{\mu} = L^{\mu}_{\nu} x^{\nu}$ (Lorentz Transformation)

such that $ds'^2 = \eta_{\mu\nu} dx'^{\mu} dx'^{\nu} = \eta_{\mu\nu} dx^{\mu} dx^{\nu} = ds^2$
 $\rightsquigarrow x'^{\mu} = L^{\mu}_1 x^1 + L^{\mu}_2 x^2 + L^{\mu}_3 x^3 + \dots$

consequence: $\eta_{\mu\nu} L^{\mu}_{\alpha} L^{\nu}_{\beta} = \eta_{\alpha\beta}$

\rightarrow it's a consequence because we already know that it's invariant!

6. LORENTZ + TRANSLATION: POINCARÉ

$$x^\mu \rightarrow x'^\mu = \Lambda^\mu_\nu x^\nu + z^\mu$$

→ Inertial reference frame are related through Poincaré Transformation

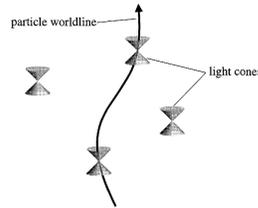
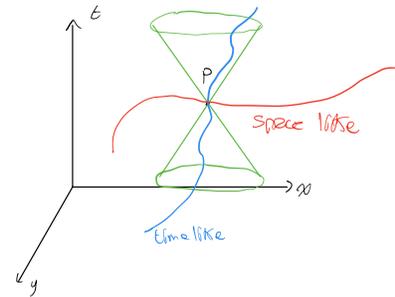
Remark

Loren/Poinc Transformations form a Group

7. DISTANCE OF 2 EVENTS

$$\Delta x^2 = \eta_{\mu\nu} (x_P^\mu - x_Q^\mu) (x_P^\nu - x_Q^\nu)$$

- if $\Delta x^2 > 0 \rightarrow P, Q$ "Time like separated"
- if $\Delta x^2 = 0 \rightarrow P, Q$ "Light like separated"
- if $\Delta x^2 < 0 \rightarrow P, Q$ "Space like separated"



8. PARAMETRIZE CURVE:

$$\lambda \rightarrow x^\mu(\lambda), \quad \lambda \in I \subseteq \mathbb{R}$$

Tangent Vector:
$$V^\mu = \frac{dx^\mu(\lambda)}{d\lambda} \quad \left(\text{More compact } V^\mu(x_0) = \left. \frac{dx^\mu(\lambda)}{d\lambda} \right|_{\lambda=\lambda_0} \right)$$

N.B: We can reparametrize curves writing $\Phi = \Psi(\lambda) \quad \Phi \in J \subseteq \mathbb{R}$

$$\Rightarrow C' = C \circ \Psi^{-1} : C(J) = C(I)$$

Basically THE CURVE remain THE SAME

Common choice:

$$\lambda : \tau = \sqrt{\eta_{\mu\nu} x^\mu x^\nu} \quad \underline{\text{PROPER TIME}}$$

but why it's good?

- it's time measured by an observer in their own Frame
- It's LORENTZ INVARIANT → other measures different time

Tangent vector of \mathbb{I} -parametrised curve:

$$\underline{\frac{d}{d\tau'} \left(x'^{\mu}(\tau') \right)} \stackrel{\tau'=\tau}{=} \frac{d}{d\tau} \left(x'^{\mu}(\tau) \right) = \frac{\partial x'^{\mu}}{\partial x^{\alpha}} \frac{dx^{\alpha}(\tau)}{d\tau} = \underline{\underline{\Lambda^{\mu}_{\alpha}}} \frac{dx^{\alpha}(\tau)}{d\tau}$$

9. LORENTZ VECTOR:

$$V'^{\mu} = \underline{\underline{\Lambda^{\mu}_{\alpha}}} V^{\alpha}$$

10. SCALAR PRODUCT

Two vectors V, W components V^{α}, W^{α}

$$\left. \begin{array}{l} \eta_{\mu\nu} V^{\mu} W^{\nu} \\ \text{Norm: } \eta_{\mu\nu} V^{\mu} V^{\nu} \end{array} \right\} \text{Lorentz Invariant} \quad \hookrightarrow \text{Notation} \quad * \quad V^{\mu} V_{\mu} = \eta_{\mu\nu} V^{\mu} V^{\nu} \quad \otimes$$

11. COVECTOR TRANSFORMS (conjugate transpose of Λ , $\Lambda \equiv (\Lambda^T)^{-1}$)

$$\Lambda^T \eta \Lambda = \eta \quad \Rightarrow \quad \Lambda = \eta \Lambda^{-1} \eta^{-1}$$

In index notation: $V'_{\alpha} = \Lambda^{\mu}_{\alpha} V_{\mu} \quad (2)$

$$\Lambda^{\mu}_{\alpha} = \eta_{\mu\beta} \Lambda^{\beta}_{\gamma} \eta^{\gamma\alpha}$$

• Covector: lower indices

Covector examples:

1) $M_{\alpha} = \eta_{\alpha\beta} V^{\beta}$ with V^{β} Lorentz vector

check if it's a covector using (2): $M'_{\alpha} = (\eta_{\alpha\beta} V^{\beta})'$

$$= \eta_{\alpha\beta} V'^{\beta} = \eta_{\alpha\beta} \Lambda^{\beta}_{\gamma} V^{\gamma} = \eta_{\alpha\beta} \Lambda^{\beta}_{\gamma} V^{\gamma}$$

But $M_{\alpha} = \eta_{\alpha\beta} V^{\beta} \Rightarrow V^{\beta} = \eta^{\beta\alpha} M_{\alpha}$

$$\Rightarrow M'_{\alpha} = \underbrace{\eta_{\alpha\beta} \Lambda^{\beta}_{\gamma} \eta^{\gamma\delta}}_{\Lambda^{\delta}_{\alpha}} M_{\delta} = \Lambda^{\delta}_{\alpha} M_{\delta}$$

2) Partial derivative of a scalar function

$$W_{,\mu} = \frac{\partial \psi}{\partial x^\mu} \text{ is a covector } (\psi(x^\mu) \text{ scalar function})$$

Ex: prove it

! Vector exist regardless of basis

$$V = V^\mu e_{(\mu)} \quad \rightarrow \quad V = V^1 e_{(1)} + V^2 e_{(2)} + V^3 e_{(3)} + V^4 e_{(4)}$$

\downarrow basis
 \downarrow basis dependent
 \downarrow basis independent components

12. TENSORS

Lorentz (p,q) tensor object that transform as a product of p vectors and q covector take

$$T_{\nu_1, \dots, \nu_q}^{\mu_1, \dots, \mu_p}$$

LTzen:

$$T_{\nu_1, \dots, \nu_q}^{\mu_1, \dots, \mu_p} = \Lambda^{\mu_1}_{\alpha_1} \dots \Lambda^{\mu_p}_{\alpha_p} \Lambda^{\beta_1}_{\nu_1} \dots \Lambda^{\beta_q}_{\nu_q} T_{\beta_1, \dots, \beta_q}^{\alpha_1, \dots, \alpha_p}$$

Examples:

1) $\eta_{\mu\nu}$: (0,2) tensor

2) $\eta^{\mu\nu}$: (2,0) tensor

3) δ^μ_ν : (1,1) tensor

Using this we can associate COVECTOR \leftrightarrow VECTOR

$$V^\mu \rightarrow V_\mu = \eta_{\mu\nu} V^\nu$$

$$V_\mu \rightarrow V^\mu = \eta^{\mu\nu} V_\nu$$

Additional property: $\eta^{\mu\nu} \eta_{\nu\rho} = \delta^\mu_\rho$ (Kroneck. delt)

4) Sums of (p,q) tensors: (p,q) tensor

5) Given $V^\mu, W^\nu, U_\rho \rightarrow V^\mu W^\nu U_\rho$ is a (2,1) tensor

WORLD LINE OF MASSIVE PARTICLE

Assuming that $x^\mu = x^\mu(\lambda)$

• **Velocity:** $V^\mu \equiv \frac{dx^\mu}{d\lambda}$ Lorentz Vector, normalized so $V^\mu V_\mu = c^2$

• **Acceleration:** $a^\mu \equiv \frac{dV^\mu}{d\lambda} = \frac{d^2 x^\mu}{d\lambda^2}$ For free particle $a^\mu = 0$

For an accelerating observer $a^\mu V_\mu = 0$

• **Action:**

For a free massive particle

$$S = -mc^2 \int d\lambda = -mc^2 \int \sqrt{\eta_{\mu\nu} dx^\mu dx^\nu}$$

(Reminder: useful due to least action principle)

With respect to an arbitrary parameter λ :

$$S = \int L_\lambda d\lambda \quad \text{where} \quad L_\lambda = -mc \left[\eta_{\mu\nu} \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda} \right]^{1/2}$$

if we chose $\lambda = t$, then

$$L_t = -mc^2 \sqrt{1 - \frac{\vec{v}^2}{c^2}}, \quad \vec{v} \equiv \frac{d\vec{x}}{dt}$$

• **Momentum:**

$$P_\mu = \frac{\partial L_\lambda}{\partial (dx^\mu/d\lambda)} = m \eta_{\mu\nu} \frac{dx^\nu}{d\lambda} \Rightarrow P_\mu = m \left(\frac{dx^\mu}{d\lambda} \right)$$

Components $P^0 = \frac{E}{c}$, $P^k = m\gamma V^k$ ($k=1,2,3$) (latin letters $\pm \rightarrow 3$)
 letters $0 \rightarrow 03$)

where $\gamma = \left(1 - \frac{\vec{v}^2}{c^2}\right)^{-1/2}$ and $E = m\gamma c^2$

$$\Rightarrow P^\mu P_\mu = m^2 c^2 \Leftrightarrow E^2 = m^2 c^4 + \vec{p}^2 c^2$$

➤ In General Relativity Space Time is a 4D MANIFOLD

Definition: Manifold M

M is a differentiable manifold M of dimension $n \in \mathbb{N}^+$

- i) M is a Hausdorff topological space (define neighborhoods which are distinct)
- ii) \exists a family of open sets $\{U_i\}$ $i \in I$ (set of index) which covers $M: \bigcup_{i \in I} U_i = M$
 \rightarrow There are spaces that covers all the manifold
- iii) Each set U_i can be mapped onto open subset of \mathbb{R}^n through a continuous INVERTIBLE map $\phi_i: U_i \rightarrow U_i' \subset \mathbb{R}^n$
- iv) Given 2 sets $U_i, U_j \subset M$ with $U_i \cap U_j \neq \emptyset$ the map $\psi_{i,j} \equiv \phi_j \circ \phi_i^{-1}$ from $\phi_i(U_i \cap U_j) \rightarrow \phi_j(U_i \cap U_j)$ is infinitely differentiable

Terminology

Chart: A pair (U_i, ϕ_i)

Atlas: The set $\{U_i, \phi_i\}$

Coordinate Neighbourhood: U_i

Coordinate Function: ϕ_i

Coordinates: In \mathbb{R}^n ϕ_i is represented by a set of Functions $X^1(p), \dots, X^n(p) \forall p \in U_i$

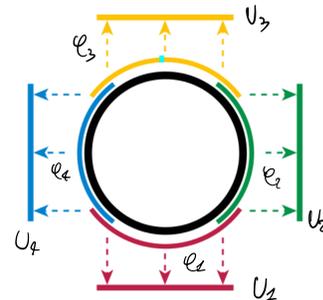


Figure 1: The four charts each map part of the circle to an open interval, and together cover the whole circle.

$$\left(\begin{array}{c} \text{blue} \\ \text{red} \\ \text{green} \\ \text{yellow} \end{array} \right) = \text{Atlas}$$

➔ This definition is telling that if I consider a differentiable MANIFOLD what I can do:

- I can rope locally $\forall p \in M$ to \mathbb{R}^n , do NORMAL TENSOR CALCULUS, map back to the manifold, move around by going into different neighborhood subspaces, define coordinates by again mapping into \mathbb{R}^n , do NORMAL CALCULUS and so on...

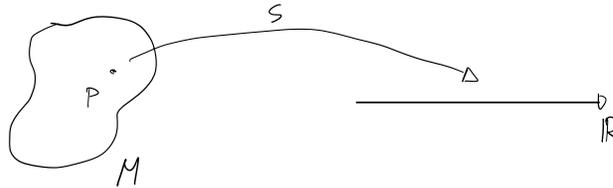
M LOCALLY LOOKS LIKE \mathbb{R}^n

Definitions

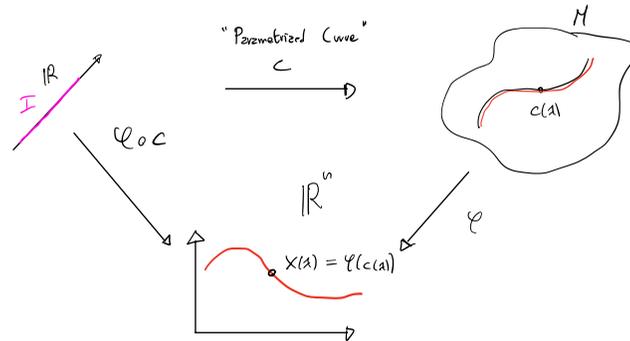
Scalar: A scalar in Space-Time is a smooth map $S: M \rightarrow \mathbb{R}$.
To each point $p \in M$ it associates a number $S(p) \in \mathbb{R}$

↳ Every observer agrees on P (in all the systems):

Under a **coordinate transformation** $X^\mu \rightarrow X'^\mu$ we have $S'(X'^\mu) = S(X^\mu)$



Curve: A parametrised curve on a M is a smooth map $c: I \subseteq \mathbb{R} \rightarrow M$ which to any real $\lambda \in I$ (parameter) associates a point in M



Co-vector: A (contravariant, tangent) **vector**

i)
$$V^{1\mu} = \frac{\partial x^{1\mu}}{\partial x^\nu} V^\nu$$
 ($\partial x^{1\mu} = \frac{\partial x^\mu}{\partial x^\nu}$)

Example:
$$dx^{1\mu} = \frac{\partial x^{1\mu}}{\partial x^\nu} dx^\nu$$

The set of all t-vectors is called Vector space T_p (Tangent Space)

Analogy $\rightarrow V = V^\mu \partial_\mu = \partial_\mu V^\mu$
 $\left\{ \begin{array}{l} \hookrightarrow \text{basis vectors} \\ \hookrightarrow \text{contravariant} \end{array} \right.$

ii) A **covector** is an object with components U_i transforming as:

$$U'_\mu = \frac{\partial x^\nu}{\partial x'^\mu} U_\nu$$

Covectors form a CO-TANGENT space

Tensors: A (p,q) tensor is an object with components

$$T^{\mu_1 \dots \mu_p}_{\nu_1 \dots \nu_q} = \frac{\partial x^{\mu_1}}{\partial x'^{\alpha_1}} \dots \frac{\partial x^{\mu_p}}{\partial x'^{\alpha_p}} \frac{\partial x^{\beta_1}}{\partial x'^{\nu_1}} \dots \frac{\partial x^{\beta_q}}{\partial x'^{\nu_q}} T^{\alpha_1 \dots \alpha_p}_{\beta_1 \dots \beta_q} \quad (p,q) \text{ Tensor}$$

Example: Kronecker $\delta^\mu_\nu = \begin{cases} 1 & \mu = \nu \\ 0 & \mu \neq \nu \end{cases}$

$$\delta^\mu_\nu = \frac{\partial x^\mu}{\partial x^\nu} = \frac{\partial x^\mu}{\partial x'^\alpha} \frac{\partial x'^\alpha}{\partial x^\nu} = \frac{\partial x^\mu}{\partial x'^\alpha} \underbrace{\frac{\partial x'^\alpha}{\partial x'^\beta}}_{\delta'^\alpha_\beta} \frac{\partial x'^\beta}{\partial x^\nu} = \frac{\partial x^\mu}{\partial x'^\alpha} \frac{\partial x'^\beta}{\partial x^\nu} \delta'^\alpha_\beta$$

$(1,1)$ Tensor $\delta'^\alpha_\beta = \frac{\partial x^\nu}{\partial x'^\beta} \frac{\partial x'^\alpha}{\partial x^\mu} \delta^\mu_\nu$

By inverting both ∂ from the derivatives

Example: Given 2 vectors V^μ, W^ν , $(V^\mu W^\nu)$ is a $(2,0)$ tensor

$$V^\mu W^\nu = \frac{\partial x'^\mu}{\partial x^\beta} V^\beta \frac{\partial x'^\nu}{\partial x^\alpha} W^\alpha = \frac{\partial x'^\mu}{\partial x^\beta} \frac{\partial x'^\nu}{\partial x^\alpha} V^\beta W^\alpha \quad (2,0) \text{ Tensor}$$

Operations with Tensors

i) Multiplication by $a \in \mathbb{R}$

if T is (p,q) -T, aT is (p,q) -T $\forall a \in \mathbb{R}$

ii) Addition of (p,q) tensors $\rightarrow (p,q)$ tensors

iii) Tensor Product: V^μ, W^ν : $V \otimes W = V^\mu W^\nu \equiv T^{\mu\nu}$

iv) Contraction of indices: $T^{\mu_1 \dots \mu_k \dots \mu_p}_{\nu_1 \dots \nu_k \dots \nu_q} \rightarrow \sum_{\text{conv}} \Rightarrow T^{\mu_1 \dots \mu_k \dots \mu_p}_{\nu_1 \dots \nu_k \dots \nu_q} + \dots + T^{\mu_1 \dots \mu_k \dots \mu_p}_{\nu_1 \dots \nu_k \dots \nu_q}$
 $= \sum_{\nu_k \dots \nu_q} T^{\mu_1 \dots \mu_p}_{\nu_k \dots \nu_q}$ *elim that index (M ≠ T)*

v) Covariant Differentiation: $S(x), V(x), T(x)$

Definition: METRIC TENSOR $g_{\mu\nu}(x)$

A (0,2) tensor field with two basic properties

1) $g_{\mu\nu}(x) = g_{\nu\mu}(x)$ (symmetric)

2) $\det [g_{\mu\nu}(x)] \neq 0$ (non-degenerate)

+ it preserves the "line element" under $x^\alpha \rightarrow x'^\alpha$:

$$ds^2(x) = g_{\mu\nu} dx^\mu dx^\nu$$

$$ds'^2(x') = g_{\mu\nu}(x') dx'^\mu dx'^\nu = ds^2$$

~ it describes the geometry of the manifold

~ it defines the scalar product

Exercise: Show that $g_{\mu\nu}$ is (0,2) tensor.

$$ds^2 = g_{\mu\nu}(x) dx^\mu dx^\nu \quad \textcircled{1}$$

$$ds'^2 = g'_{\mu\nu}(x) dx'^\mu dx'^\nu \quad \textcircled{2}$$

but $dx'^\mu = \frac{\partial x'^\mu}{\partial x^\alpha} dx^\alpha \Rightarrow dx^\alpha = \frac{\partial x^\alpha}{\partial x'^\mu} dx'^\mu \quad \textcircled{3}$

and $dx'^\nu = \frac{\partial x'^\nu}{\partial x^\beta} dx^\beta \Rightarrow dx^\beta = \frac{\partial x^\beta}{\partial x'^\nu} dx'^\nu \quad \textcircled{4}$

$$\begin{aligned} 1, 2, 3 \Rightarrow ds^2 &= g_{\mu\nu}(x) \frac{\partial x^\mu}{\partial x'^\alpha} \frac{\partial x^\nu}{\partial x'^\beta} dx'^\alpha dx'^\beta \\ &= g_{\alpha\beta}(x) \frac{\partial x^\alpha}{\partial x'^\mu} \frac{\partial x^\beta}{\partial x'^\nu} dx'^\mu dx'^\nu \end{aligned}$$

From $\textcircled{2}$ we have $ds'^2 = ds^2$ so

$$g'_{\mu\nu}(x) = \frac{\partial x^\alpha}{\partial x'^\mu} \frac{\partial x^\beta}{\partial x'^\nu} g_{\alpha\beta}(x) \quad (0,2) \text{ tensor}$$

Definition: INVERSE METRIC

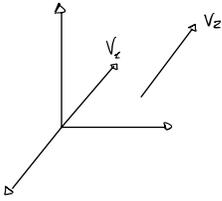
$$g_{\mu\nu} g^{\nu\alpha} = \delta_\mu^\alpha$$

Raising / Lowering indices:

1) From a vector V^μ we can construct a covector $V_\mu \equiv g_{\mu\nu} V^\nu$

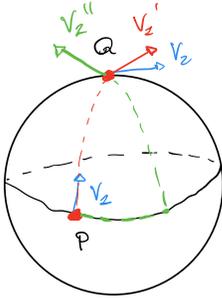
2) Given the inverse metric, a covector V_μ we can construct a vector $V^\mu = g^{\mu\nu} V_\nu$

MANIFOLD



If you want to compare 2 vectors in \mathbb{R}^2 , you take v_2 and translate it near v_1

We want to do the same in MANIFOLD



Now on a surface I want to do the same, so I connect the 2 points and translate along that path, v_1 become v_2

Another path could be the green, but the 2 translation gives 2 diff vectors

→ The Final vector DEPENDS on the PATH

Considering a vector A with components A^μ , the $\partial_\nu A^\mu$ is Tensor?

$$\begin{aligned} \text{So } \left. \begin{aligned} \partial_\mu A^\nu &= \frac{\partial x^\alpha}{\partial x'^\mu} \frac{\partial}{\partial x^\alpha} \left(\frac{\partial x'^\nu}{\partial x^\beta} A^\beta \right) \\ A'^\mu &= \frac{\partial x'^\mu}{\partial x^\beta} A^\beta \end{aligned} \right\} \begin{aligned} &= \partial'_\mu A'^\nu \\ &= \frac{\partial x^\alpha}{\partial x'^\mu} \frac{\partial}{\partial x^\alpha} \left(\frac{\partial x'^\nu}{\partial x^\beta} A^\beta \right) \\ &= \underbrace{\frac{\partial x^\alpha}{\partial x'^\mu} \frac{\partial x'^\nu}{\partial x^\beta} \partial_\alpha A^\beta}_{\text{Tensor-like}} + \underbrace{\frac{\partial x^\alpha}{\partial x'^\mu} \frac{\partial^2 x'^\nu}{\partial x^\alpha \partial x^\beta} A^\beta}_{\text{Not tensor}} \end{aligned}$$

⇒ Partial Derivatives is not a Tensor

Theorem: For every metric $g_{\mu\nu}$ it's always possible to Find coordinates

("Riemann norm .. coordinates) such that at one point $P = x_0 \equiv 0 \equiv x'_0$:

- 1) $g'_{\mu\nu}(x'_0) = \eta_{\mu\nu}$
- 2) $\partial_{x'^\rho} g'_{\mu\nu} |_{x'_0} = 0$
- 3) $\partial_{x'^\rho} \partial_{x'^\sigma} g'_{\mu\nu} (x'_0) \neq 0$ unless the space is flat

Definition: COVARIANT DERIVATIVE

$$D_\mu A^\nu \equiv \partial_\mu A^\nu + \Gamma_{\mu\lambda}^\nu A^\lambda$$

→ Demand to be a tensor

↳ How much the coordinate change
 ↳ "How much the vector changes"
 ↑: "Christoffel symbol"
 "A fine connection coefficient"

• Christoffel symbol is a tensor?

Answer: $\Gamma_{\mu\lambda}^\nu \rightarrow$ Not Tensor. Proof why:

- Useful relations:

$$1. D_\mu V^\nu \equiv \partial_\mu V^\nu + \Gamma_{\mu\lambda}^\nu V^\lambda$$

$$2. V'^\mu = \frac{\partial x'^\mu}{\partial x^\nu} V^\nu \Leftrightarrow V^\nu = \frac{\partial x^\nu}{\partial x'^\mu} V'^\mu$$

$$3. V'_\mu = \frac{\partial x^\alpha}{\partial x'^\mu} V_\alpha \Leftrightarrow V_\alpha = \frac{\partial x'^\mu}{\partial x^\alpha} V'_\mu$$

$$4. T'^\mu{}_\nu = \frac{\partial x'^\mu}{\partial x^\alpha} \frac{\partial x^\beta}{\partial x'^\nu} T^\alpha{}_\beta \Rightarrow T^\alpha{}_\beta = \frac{\partial x^\alpha}{\partial x'^\mu} \frac{\partial x'^\nu}{\partial x^\beta} T'^\mu{}_\nu$$

$$D_\mu V^\nu \stackrel{\textcircled{4}}{=} \frac{\partial x^\nu}{\partial x'^\mu} \frac{\partial x'^\beta}{\partial x^\alpha} (D_\beta V'^\alpha)$$

$$\stackrel{\textcircled{1}}{=} \frac{\partial x^\nu}{\partial x'^\mu} \frac{\partial x'^\beta}{\partial x^\alpha} \left[\frac{\partial V'^\alpha}{\partial x^\beta} + \Gamma_{\beta\gamma}^\alpha V'^\gamma \right]$$

let's see how $\left[\right]$ transforms

$$\bullet \left(\frac{\partial V'^\alpha}{\partial x^\beta} + \Gamma_{\beta\gamma}^\alpha V'^\gamma \right) \stackrel{\textcircled{5}}{=} \frac{\partial x^k}{\partial x'^\beta} \frac{\partial x'^\alpha}{\partial x^\gamma} \frac{\partial V'^\gamma}{\partial x^k} + \frac{\partial x^k}{\partial x'^\beta} \frac{\partial^2 x'^\alpha}{\partial x^k \partial x^\gamma} V'^\gamma + \Gamma_{\beta\gamma}^\alpha \frac{\partial x'^\rho}{\partial x^\gamma} V'^\rho$$

From 3. For W^α

From last page ↑

Then:

$$D_\mu V^\nu = \frac{\partial x^\nu}{\partial x'^\mu} \frac{\partial x'^\beta}{\partial x^\alpha} \left[\frac{\partial x^k}{\partial x'^\beta} \frac{\partial x'^\alpha}{\partial x^\gamma} \frac{\partial V'^\gamma}{\partial x^k} + \frac{\partial x^k}{\partial x'^\beta} \frac{\partial^2 x'^\alpha}{\partial x^k \partial x^\gamma} V'^\gamma + \Gamma_{\beta\gamma}^\alpha \frac{\partial x'^\rho}{\partial x^\gamma} V'^\rho \right]$$

but $\frac{\partial x^\mu}{\partial x'^\alpha} \frac{\partial x'^\alpha}{\partial x^\nu} = \frac{\partial x^\mu}{\partial x^\nu} = \delta^\mu_\nu$

$\Rightarrow D_\alpha V^\nu = \delta^\nu_\alpha \delta^\mu_\mu \partial_\mu V^\alpha + \delta^\mu_\alpha \frac{\partial x^\nu}{\partial x'^\mu} \frac{\partial^2 x^\nu}{\partial x^\mu \partial x^\alpha} V^\mu + \frac{\partial x^\nu}{\partial x'^\alpha} \frac{\partial x'^\beta}{\partial x^\mu} \frac{\partial x'^\mu}{\partial x^\alpha} \Gamma^\nu_{\beta\gamma} V^\gamma$

Using $\delta^\nu_\alpha V^\alpha = V^\nu$

$\Rightarrow D_\alpha V^\nu = \partial_\alpha V^\nu + \frac{\partial x^\nu}{\partial x'^\alpha} \frac{\partial^2 x'^\alpha}{\partial x^\mu \partial x^\alpha} V^\mu + \frac{\partial x^\nu}{\partial x'^\alpha} \frac{\partial x'^\beta}{\partial x^\mu} \frac{\partial x'^\mu}{\partial x^\alpha} \Gamma^\nu_{\beta\gamma} V^\gamma$ (A)

And $D_\mu V^\nu \equiv \partial_\mu V^\nu + \Gamma^\nu_{\mu\alpha} V^\alpha$ (1)

(A) and (1) must hold $\forall x$ so:

$\Gamma^\nu_{\mu\alpha} = \frac{\partial x^\nu}{\partial x'^\alpha} \frac{\partial^2 x'^\alpha}{\partial x^\mu \partial x^\alpha} + \frac{\partial x^\nu}{\partial x'^\alpha} \frac{\partial x'^\beta}{\partial x^\mu} \frac{\partial x'^\mu}{\partial x^\alpha} \Gamma^\nu_{\beta\gamma} \Rightarrow$ rearrange

$\Gamma^\nu_{\beta\gamma} = \underbrace{\frac{\partial x'^\alpha}{\partial x^\beta} \frac{\partial x^\mu}{\partial x'^\gamma} \frac{\partial x^\alpha}{\partial x'^\mu}}_{\text{Tensor-like}} \Gamma^\nu_{\mu\alpha} - \underbrace{\frac{\partial x^\mu}{\partial x'^\beta} \frac{\partial x^\alpha}{\partial x'^\gamma} \frac{\partial^2 x'^\alpha}{\partial x^\mu \partial x^\alpha}}_{\text{NOT Tensor like}}$

Consider $\Gamma^\nu_{\mu\alpha}, \bar{\Gamma}^\nu_{\mu\alpha} = \Gamma^\nu_{\alpha\mu}$

$T_{\mu\alpha}^\nu \equiv \Gamma^\nu_{\mu\alpha} - \bar{\Gamma}^\nu_{\mu\alpha} \rightarrow$ "Torsion" Exercise: Prove T is a (1,2) tensor

$$T_{\alpha\mu}^\nu = \Gamma^\nu_{\mu\alpha} - \Gamma^\nu_{\alpha\mu} = \frac{\partial x'^\alpha}{\partial x^\beta} \frac{\partial x^\mu}{\partial x'^\gamma} \frac{\partial x^\alpha}{\partial x'^\mu} \Gamma^\nu_{\mu\alpha} - \frac{\partial x^\mu}{\partial x'^\beta} \frac{\partial x^\alpha}{\partial x'^\gamma} \frac{\partial^2 x'^\alpha}{\partial x^\mu \partial x^\alpha} -$$

$$- \left(\frac{\partial x'^\alpha}{\partial x^\beta} \frac{\partial x^\alpha}{\partial x'^\gamma} \frac{\partial x^\mu}{\partial x'^\mu} \Gamma^\nu_{\alpha\mu} - \frac{\partial x^\alpha}{\partial x'^\beta} \frac{\partial x^\mu}{\partial x'^\gamma} \frac{\partial^2 x'^\alpha}{\partial x^\alpha \partial x^\mu} \right)$$

$$= \frac{\partial x'^\alpha}{\partial x^\beta} \frac{\partial x^\mu}{\partial x'^\gamma} \frac{\partial x^\alpha}{\partial x'^\mu} (\Gamma^\nu_{\mu\alpha} - \Gamma^\nu_{\alpha\mu}) \quad (1,2) \text{ Tensor}$$
Dummy index

Definition: PARTIAL DERIVATIVE ALONG ANOTHER VECTOR

$$D_A V^\mu = A^\nu \partial_\nu V^\mu$$

Definition: COVARIANT DERIVATIVE OF (p,q) TENSORS

1) D_μ is a linear operator that takes $(p,q) \rightarrow (p,q \pm 1)$ tensor

2) If S is a scalar $D_\mu S = \partial_\mu S$

$$3) D_\mu (A_{\nu_1 \dots \nu_p}^{s_1 \dots s_r} B_{\lambda_1 \dots \lambda_q}^{t_1 \dots t_s}) = (D_\mu A_{\nu_1 \dots \nu_p}^{s_1 \dots s_r}) B_{\lambda_1 \dots \lambda_q}^{t_1 \dots t_s} + A_{\nu_1 \dots \nu_p}^{s_1 \dots s_r} (D_\mu B_{\lambda_1 \dots \lambda_q}^{t_1 \dots t_s})$$

Note That: $D_\mu U_\nu = \partial_\mu U_\nu - \Gamma_{\mu\nu}^\lambda U_\lambda$

$$U_\nu = \delta_{\nu\mu} U^\mu$$

Dim: scalar $A_\nu B^\nu$, with $D_\mu(A_\nu B^\nu) = \partial_\mu(A_\nu B^\nu)$

$$= (D_\mu A_\nu) B^\nu + A_\nu (D_\mu B^\nu)$$

$$= (D_\mu A_\nu) B^\nu + A_\nu (\partial_\mu B^\nu + \Gamma_{\mu\lambda}^\nu B^\lambda) = \partial_\mu(A_\nu B^\nu)$$

$$= (D_\mu A_\nu) B^\nu + A_\nu (\cancel{\partial_\mu B^\nu}) + A_\nu \Gamma_{\mu\lambda}^\nu B^\lambda = \partial_\mu(A_\nu B^\nu)$$

$$= (D_\mu A_\nu) B^\nu + A_\nu (\cancel{\partial_\mu B^\nu})$$

$$\leadsto (D_\mu A_\nu) B^\nu + A_\nu \Gamma_{\mu\lambda}^\nu B^\lambda = (D_\mu A_\nu) B^\nu$$

Exer: Prove this

Tip: Consider $D_\mu V^\mu \oplus$ use 1), 2), 3)

$$(D_\mu A_\nu) B^\nu = (D_\mu A_\nu) B^\nu - A_\nu \Gamma_{\mu\lambda}^\nu B^\lambda$$

Covariant Derivative of (p,q) tensor:

$$D_\mu T_{\beta_1 \dots \beta_q}^{\alpha_1 \dots \alpha_p} = \partial_\mu T_{\beta_1 \dots \beta_q}^{\alpha_1 \dots \alpha_p} + \Gamma_{\mu\lambda}^{\alpha_1} T_{\beta_1 \dots \beta_q}^{\lambda \dots \alpha_p} + \dots + \Gamma_{\mu\lambda}^{\alpha_p} T_{\beta_1 \dots \beta_q}^{\alpha_1 \dots \lambda} - \Gamma_{\mu\lambda}^{\beta_1} T_{\lambda \beta_2 \dots \beta_q}^{\alpha_1 \dots \alpha_p} - \dots - \Gamma_{\mu\lambda}^{\beta_q} T_{\beta_1 \dots \beta_{q-1} \lambda}^{\alpha_1 \dots \alpha_p}$$

Properties of D_μ

i) D_μ commutes with index contraction

ii) $D_\alpha g_{\mu\nu} = 0$

iii) D_μ commutes with raising and lowering indices

iv) D_μ commutes with scalar $D_\mu D_\nu S = D_\nu D_\mu S$

Christoffen symbol

$$D_{\mu} g_{\rho\sigma} = \partial_{\mu} g_{\rho\sigma} - \underbrace{\Gamma_{\mu\rho}^{\lambda} g_{\lambda\sigma}} - \underbrace{\Gamma_{\mu\sigma}^{\lambda} g_{\rho\lambda}} \stackrel{(ii)}{=} 0$$

$$D_{\rho} g_{\sigma\mu} = \partial_{\rho} g_{\sigma\mu} - \underbrace{\Gamma_{\rho\sigma}^{\lambda} g_{\lambda\mu}} - \underbrace{\Gamma_{\rho\mu}^{\lambda} g_{\sigma\lambda}} \stackrel{(ii)}{=} 0$$

$$D_{\sigma} g_{\mu\rho} = \partial_{\sigma} g_{\mu\rho} - \underbrace{\Gamma_{\sigma\mu}^{\lambda} g_{\lambda\rho}} - \underbrace{\Gamma_{\sigma\rho}^{\lambda} g_{\mu\lambda}} \stackrel{(iii)}{=} 0$$

~> Reminders: $g_{\mu\nu} = g_{\nu\mu}$ and in GR we always consider torsion-free

So $\textcircled{1} - \textcircled{2} - \textcircled{3} = 0$

$$\Rightarrow \Gamma_{\rho\sigma}^{\lambda} = \frac{1}{2} (\partial_{\rho} g_{\sigma\mu} + \partial_{\sigma} g_{\rho\mu} - \partial_{\mu} g_{\rho\sigma}) g^{\lambda\mu}$$

$\cdot g_{\lambda\mu} \rightarrow$

$$\Gamma_{\mu\rho}^{\lambda} = \Gamma_{\rho\mu}^{\lambda} = \frac{1}{2} (\partial_{\sigma} g_{\mu\rho} + \partial_{\rho} g_{\sigma\mu} - \partial_{\mu} g_{\rho\sigma})$$

Parallel Transport (or Covariant Differentiation Along the curve)

Let $c:]a,b[\subseteq \mathbb{R} \rightarrow U \subset M$ be a parametrised curve in an open subset of M which, in a given coordinate system reads $x^\mu(\lambda), \lambda \in \mathbb{R}$.

We say that a vector V is parallel transported along C if

$$\frac{DV^\mu}{d\lambda} \equiv \frac{dx^\nu}{d\lambda} D_\nu V^\mu = 0 \quad \text{"everywhere along the curve"}$$

The curve $D_\lambda V^\mu$ Tangent Vector to the curve "velocity"

Parallel Transport preserve:

Using $D_\lambda g_{\mu\nu} = 0$ we have $g_{\mu\nu} V^\mu V^\nu = \text{constant}$ "Norm of vectors"

also $g_{\mu\nu} V^\mu U^\nu = \text{const}$ "Scalar Product"

also ANGLES REMAINS CONSTANTS

- If we get the cov derivative along the curve, allow us to define

"Covariant Acceleration"

$$a^\mu = \frac{DV^\mu}{d\lambda} = \frac{D\dot{x}^\mu}{d\lambda} = \ddot{x}^\mu + \Gamma_{\nu\lambda}^\mu \dot{x}^\nu \dot{x}^\lambda = V^\nu D_\nu V^\mu$$

$\leadsto \dot{x}^\mu = \frac{dx^\mu}{d\lambda}$

Definition Geodesic

$$\frac{d^2 x^\mu}{d\lambda^2} - \Gamma_{\nu\lambda}^\mu \frac{dx^\nu}{d\lambda} \frac{dx^\lambda}{d\lambda} = 0$$

It's a curve of zero acceleration

Is what would have been a straight path in a flat space!

LET'S SHOW THAT

$$ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta$$

$$d\tau^2 = -ds^2$$

$$\dot{C}_{AB} = \int_A^B \sqrt{d\tau^2} = \int_A^B \sqrt{g_{\alpha\beta} dx^\alpha dx^\beta}$$

Consider worldline $x^\alpha \equiv x^\alpha(\tau)$ from $\tau=0$ to $\tau=1$

$$\dot{C}_{AB} = \int_0^1 \left[-g_{\alpha\beta} \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} \right]^{1/2} d\tau = \int_A^B \mathcal{L} \left[x^\alpha, \frac{dx^\alpha}{d\tau} \right] d\tau$$

Lets consider a Lagrangian $\rightarrow \mathcal{L} \equiv \left[-g_{\alpha\beta} \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} \right]^{1/2} = \frac{dF}{d\tau}$

Note that $\forall f = f(\tau)$ we have $\frac{dF}{d\tau} = \frac{dF}{d\tau} \frac{d\tau}{d\tau} = \mathcal{L} \frac{dF}{d\tau}$ $\textcircled{1}$

EULER LAGRANGIAN EQUATION

$$\frac{\partial \mathcal{L}}{\partial x^\alpha} - \frac{d}{d\tau} \left[\frac{\partial \mathcal{L}}{\partial (dx^\alpha/d\tau)} \right] = 0$$

1^o TERM

$$\frac{\partial \mathcal{L}}{\partial x^\alpha} = -\frac{1}{2\mathcal{L}} \frac{\partial g_{\alpha\beta}}{\partial x^\alpha} \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} \stackrel{\textcircled{1}}{=} -\frac{\mathcal{L}}{2} \frac{\partial g_{\alpha\beta}}{\partial x^\alpha} \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} \quad \leadsto \frac{dx^\alpha}{d\tau} = \mathcal{L} \frac{dx^\alpha}{d\tau}$$

2^o TERM

$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial (dx^\alpha/d\tau)} &= -\frac{1}{2\mathcal{L}} \underline{g_{\alpha\beta}} \left(\frac{dx^\beta}{d\tau} \underline{\partial_{\alpha\tau}} + \frac{dx^\alpha}{d\tau} \underline{\partial_{\beta\tau}} \right) & \partial_{\alpha\tau} &= \frac{\partial x^\alpha}{\partial x^\tau} \\ &= -\frac{1}{2\mathcal{L}} \left(\underline{g_{\alpha\beta}} \frac{dx^\beta}{d\tau} + \underline{g_{\alpha\alpha}} \frac{dx^\alpha}{d\tau} \right) \\ &= -\frac{1}{\mathcal{L}} \underline{g_{\alpha\alpha}} \frac{dx^\alpha}{d\tau} & \leadsto \text{Metric is symmetric} \end{aligned}$$

Deriving of \mathcal{L} Term

$$\begin{aligned}
 \frac{d}{d\tau} \left[\frac{\partial L}{\partial (dx^\alpha/d\tau)} \right] &= \frac{d}{d\tau} \left[-\frac{1}{L} g_{\alpha\gamma} \frac{dx^\alpha}{d\tau} \right] \\
 &\stackrel{(\gamma)}{=} \frac{d}{d\tau} \left[-\frac{1}{L} g_{\alpha\gamma} \frac{dx^\alpha}{d\tau} \right] \\
 &= \frac{d}{d\tau} \left[g_{\alpha\gamma} \frac{d^2 x^\alpha}{d\tau^2} + \frac{dg_{\alpha\gamma}}{d\tau} \frac{dx^\alpha}{d\tau} \right] \\
 &= \frac{d}{d\tau} \left[g_{\alpha\gamma} \frac{d^2 x^\alpha}{d\tau^2} + \frac{\partial g_{\alpha\gamma}}{\partial x^\beta} \frac{dx^\beta}{d\tau} \frac{dx^\alpha}{d\tau} \right] \\
 &= \frac{d}{d\tau} \left[g_{\alpha\gamma} \frac{d^2 x^\alpha}{d\tau^2} + \frac{1}{2} \left[\frac{\partial g_{\alpha\gamma}}{\partial x^\beta} + \frac{\partial g_{\gamma\beta}}{\partial x^\alpha} \right] \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} \right]
 \end{aligned}$$

Lagrange Equation:

$$\begin{aligned}
 \frac{\partial L}{\partial x^\alpha} - \frac{d}{d\tau} \left[\frac{\partial L}{\partial (dx^\alpha/d\tau)} \right] &= \frac{d}{d\tau} \left[g_{\alpha\gamma} \frac{d^2 x^\alpha}{d\tau^2} + \frac{1}{2} \left(\frac{\partial g_{\alpha\gamma}}{\partial x^\beta} + \frac{\partial g_{\gamma\beta}}{\partial x^\alpha} \right) \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} \right] - \\
 &\quad - \frac{1}{2} \frac{\partial g_{\alpha\beta}}{\partial x^\gamma} \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} = 0
 \end{aligned}$$

$$\begin{aligned}
 \Rightarrow g_{\alpha\gamma} \frac{d^2 x^\alpha}{d\tau^2} &= -\frac{1}{2} \left[\frac{\partial g_{\alpha\gamma}}{\partial x^\beta} + \frac{\partial g_{\gamma\beta}}{\partial x^\alpha} - \frac{\partial g_{\alpha\beta}}{\partial x^\gamma} \right] \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} = \\
 &= -\frac{1}{2} \left[\frac{\partial g_{\alpha\gamma}}{\partial x^\beta} + \frac{\partial g_{\gamma\beta}}{\partial x^\alpha} - \frac{\partial g_{\alpha\beta}}{\partial x^\gamma} \right] \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} = \\
 &= -\frac{1}{2} g_{\alpha\gamma} \Gamma_{\beta\gamma}^{\alpha} \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau}
 \end{aligned}$$

$$\Rightarrow \boxed{\frac{d^2 x^\alpha}{d\tau^2} = -\frac{1}{2} \Gamma_{\beta\gamma}^{\alpha} \frac{dx^\beta}{d\tau} \frac{dx^\gamma}{d\tau}} \quad \square$$

If we define $\mathcal{L}_1 = \frac{\mathcal{L}^2}{2}$ it's been shown that also satisfies *Eul-Lag*.

Geodesics of Flat S-T in Cartesian Polar Coordinates

$$ds^2 = dx^2 + dy^2 = dr^2 + r^2 d\varphi^2$$

i) Cartesian
$$\begin{array}{l} g_{xx} = 1 \\ g_{yy} = 1 \end{array} \quad g_{xy} = 0 = g_{yx} \quad \left| \quad \begin{array}{l} g_{xx} = 1 \\ g_{yy} = 1 \end{array} \quad g_{xy} = 0 = g_{yx} \right.$$

2) Polar
$$\begin{array}{l} g_{rr} = 1 \\ g_{\varphi\varphi} = r^2 \end{array} \quad g_{r\varphi} = 0 = g_{\varphi r} \quad \left| \quad \begin{array}{l} g_{rr} = 1 \\ g_{\varphi\varphi} = r^2 \end{array} \quad g_{r\varphi} = 0 = g_{\varphi r} \right.$$

Geodesic equation:

1) Cartesian

All Γ symbols are zero ($g_{\mu\nu} = \delta_{\mu\nu} \rightarrow \text{All } \partial_\sigma g_{\mu\nu} = 0$)

$$\rightarrow \frac{d^2 x}{d\lambda^2} = \frac{d^2 y}{d\lambda^2} = 0$$

2) Polar

$$\begin{array}{l} \partial_r g_{rr} = 0 \\ \partial_r g_{r\varphi} = 0 \\ \partial_r g_{\varphi\varphi} = 2r \end{array} \quad \partial_\varphi g_{\mu\nu} = 0 \quad \forall \mu, \nu = r, \varphi$$

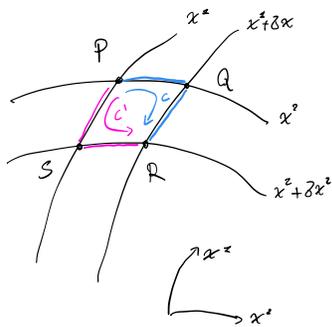
$$\Rightarrow \Gamma_{\varphi\varphi}^r = -r \quad \Gamma_{r\varphi}^\varphi = \frac{1}{r} \quad \Gamma_{\varphi r}^\varphi = \frac{1}{r} \quad (\text{symmetric})$$

$$\leadsto \frac{d^2 r}{d\lambda^2} + \Gamma_{\varphi\varphi}^r \left(\frac{d\varphi}{d\lambda} \right)^2 = 0 \quad \Rightarrow \ddot{r} - r\dot{\varphi}^2 = 0$$

$$\frac{d^2 \varphi}{d\lambda^2} + 2\Gamma_{r\varphi}^\varphi \frac{dr}{d\lambda} \frac{d\varphi}{d\lambda} = 0 \quad \Rightarrow \ddot{\varphi} + \frac{2}{r} \dot{r}\dot{\varphi} = 0$$

Even in Flat Space There are $\neq 0$ Christoffel Symbols

Transport Vectors on curved space



Remind: $D_\alpha V^\mu = \partial_\alpha V^\mu + \Gamma_{\alpha\lambda}^\mu V^\lambda$ Covariant Derivative

$\frac{dx^\mu}{dx^\alpha} D_\alpha V^\mu = 0$ Parallel Transport

i) Parallel Transport along $P \rightarrow Q$

Only x^2 changes

$$\frac{dx^\mu}{dx^1} D_\alpha V^\mu = \frac{dx^2}{dx^1} D_2 V^\mu + \frac{dx^1}{dx^1} D_1 V^\mu = 0$$

So $\frac{dx^2}{dx^1} D_2 V^\mu = 0 = \frac{dx^2}{dx^1} [\partial_2 V^\mu + \Gamma_{21}^\mu V^1]$ $|_{x^1 \text{ constant}}$

$$\Rightarrow \frac{dV^\mu}{dx^2} \Big|_{x^2} = -\Gamma_{21}^\mu V^1 \Rightarrow \int_{x^2}^{x^2 + \delta x^2} \frac{dV^\mu}{dx^2} dx^2 = - \int \Gamma_{21}^\mu V^1 dx^2 \Big|_{x^2}$$

$$\Rightarrow V_c^\mu(Q) - V_c^\mu(P) = - \int \Gamma_{21}^\mu V^1 dx^2 \Big|_{x^2}$$

$$\Rightarrow V_c^\mu(Q) = V_c^\mu(P) - \underbrace{\int \Gamma_{21}^\mu V^1 dx^2 \Big|_{x^2}}_{\equiv I_2} \quad (3)$$

ii) Parallel transport $Q \rightarrow R$, x^1 is constant

Like before $\frac{dx^\mu}{dx^1} D_2 V^\mu = 0 \Rightarrow \frac{dx^2}{dx^1} [\partial_2 V^\mu + \Gamma_{21}^\mu V^1] = 0$

$$\dots \Rightarrow V_c^\mu(R) = V_c^\mu(Q) - \underbrace{\int_{x^2}^{x^2 + \delta x^2} \Gamma_{21}^\mu V^1 dx^2 \Big|_{x^1}}_{\equiv I_2} \quad (4)$$

iii) Parallel Transport P \rightarrow S

$$V_c^\mu(S) = V_c^\mu(P) - \underbrace{\int_{x^2}^{x^2 + \delta x^2} \Gamma_{2\alpha}^\mu V^\alpha dx^2}_{= I_3} \quad (5)$$

iv) Parallel Transport S \rightarrow R

$$V_c^\mu(R) = V_c^\mu(S) - \underbrace{\int_{x^1}^{x^1 + \delta x^1} \Gamma_{1\alpha}^\mu V^\alpha dx^1}_{= I_4} \quad (6)$$

We want to calculate difference

$$\begin{aligned} V_c^\mu(R) - V_c^\mu(Q) &= V_c^\mu(Q) - I_2 - V_c^\mu(S) + I_4 = \\ &= \cancel{V_c^\mu(P)} - I_1 - I_2 - \cancel{V_c^\mu(P)} + I_3 + I_4 = \\ &= I_3 - I_1 + I_4 - I_2 = \\ &= \underbrace{\int_{x^1}^{x^1 + \delta x^1} (\Gamma_{1\alpha}^\mu V^\alpha|_{x^1 + \delta x^1} - \Gamma_{1\alpha}^\mu V^\alpha|_{x^1}) dx^1}_{I_{41}} + \underbrace{\int_{x^2}^{x^2 + \delta x^2} (\Gamma_{2\alpha}^\mu V^\alpha|_{x^2} - \Gamma_{2\alpha}^\mu V^\alpha|_{x^2 + \delta x^2}) dx^2}_{I_{32}} \end{aligned}$$

In the limit δx^1 and δx^2 are small we can Taylor expand integrals

$$\Gamma_{2\alpha}^\mu V^\alpha|_{x^2 + \delta x^2} \approx \Gamma_{2\alpha}^\mu V^\alpha|_{x^2} + \left[\frac{\partial}{\partial x^2} (\Gamma_{2\alpha}^\mu V^\alpha) \right]_{x^2} \delta x^2$$

$$\Gamma_{1\alpha}^\mu V^\alpha|_{x^1 + \delta x^1} \approx \Gamma_{1\alpha}^\mu V^\alpha|_{x^1} + \left[\frac{\partial}{\partial x^1} (\Gamma_{1\alpha}^\mu V^\alpha) \right]_{x^1} \delta x^1$$

So

$$I_{41} = \delta x^1 \int_{x^1}^{x^1 + \delta x^1} \left[\frac{\partial}{\partial x^1} (\Gamma_{1\alpha}^\mu V^\alpha) \right]_{x^1} dx^1$$

$$I_{32} = -\delta x^2 \int_{x^2}^{x^2 + \delta x^2} \left[\frac{\partial}{\partial x^2} (\Gamma_{2\alpha}^\mu V^\alpha) \right]_{x^2} dx^2$$

For small $\delta x^{a,2}$ we consider the integral to be constant ...

$$I_{41} \approx \delta x^2 \delta x^1 \left[\partial_2 (\Gamma_{21}^\alpha V^1) \right]_{x^2}$$

$$I_{32} \approx -\delta x^1 \delta x^2 \left[\partial_1 (\Gamma_{12}^\alpha V^2) \right]_{x^1}$$

Open up the parenthesis

$$I_{32} = -\delta x^1 \delta x^2 \left(\partial_1 \Gamma_{12}^\alpha V^2 + \Gamma_{12}^\alpha \partial_1 V^2 \right)$$

Using $\frac{dV^\alpha}{dx} = -\Gamma_{\alpha\beta}^\alpha V^\beta \dots$

$$= -\delta x^1 \delta x^2 \left(\partial_1 \Gamma_{12}^\alpha V^2 + \Gamma_{12}^\alpha (-\Gamma_{1\alpha}^\beta V^\beta) \right)$$

$$= -\delta x^1 \delta x^2 \left(\partial_1 \Gamma_{12}^\alpha - \Gamma_{1\alpha}^\beta \Gamma_{12}^\alpha \right) V^2 \quad \text{swapped } \alpha \text{ and } \beta$$

Similarly

$$I_{41} = \delta x^2 \delta x^1 \left(\partial_2 \Gamma_{21}^\alpha - \Gamma_{2\alpha}^\beta \Gamma_{21}^\alpha \right) V^1$$

In the end:

$$V_c^\alpha(R) - V_c^\alpha(R) = \delta x^2 \delta x^1 \left(\partial_1 \Gamma_{12}^\alpha - \partial_2 \Gamma_{21}^\alpha + \Gamma_{12}^\beta \Gamma_{\beta 1}^\alpha - \Gamma_{21}^\beta \Gamma_{2\beta}^\alpha \right) V^\alpha$$

But nothing special in 1 or 2 ...

$$\begin{matrix} 1 \rightarrow \partial_1 \\ 2 \rightarrow \partial_2 \end{matrix}$$

$$V_c^\alpha(R) - V_c^\alpha(R) = \delta x^1 \delta x^2 R_{\mu\nu}^\alpha(P) V^\mu(P)$$

where $R_{\mu\nu}^\alpha(P)$ is the Riemann Tensor

$$R_{\mu\nu}^\alpha(P) = \partial_\mu \Gamma_{\nu\alpha}^\alpha - \partial_\nu \Gamma_{\mu\alpha}^\alpha + \Gamma_{\mu\alpha}^\beta \Gamma_{\beta\nu}^\alpha - \Gamma_{\nu\alpha}^\beta \Gamma_{\beta\mu}^\alpha$$

Properties

1) Is a tensor

2) $R_{\nu\mu}^\alpha = -R_{\mu\nu}^\alpha$

3) $R_{\mu\nu\sigma}^\alpha = -R_{\nu\mu\sigma}^\alpha$ where $R_{\mu\nu\sigma}^\alpha = g^{\alpha\lambda} R_{\lambda\mu\nu}^\sigma$

4) $R_{\nu\mu}^\alpha + R_{\sigma\nu}^\alpha + R_{\mu\sigma}^\alpha = 0$

5) $R_{\mu\nu\sigma}^\alpha + R_{\mu\sigma\nu}^\alpha + R_{\nu\sigma\mu}^\alpha = 0$

6) $R_{\mu\nu\sigma}^\alpha = R_{\sigma\mu\nu}^\alpha$

5) Bianchi identity

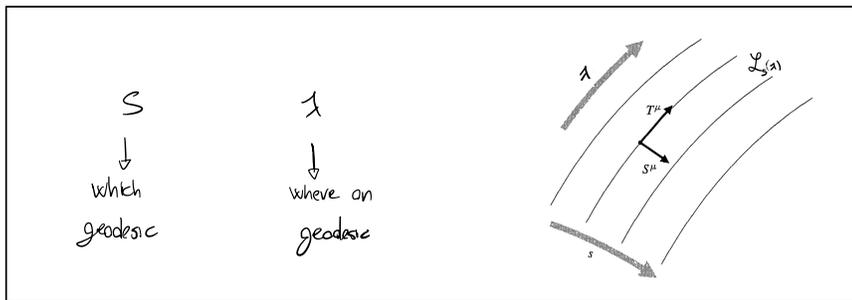
$$D_\mu R_{\nu\sigma}^\alpha + D_\nu R_{\mu\sigma}^\alpha + D_\sigma R_{\mu\nu}^\alpha = 0$$

Geodesic Deviation

- L_0 parametrized by λ

$$T^\mu = \frac{dx^\mu}{d\lambda} \rightarrow \text{tangent vector}$$

- Consider $\{L\}$ Family of geodesics, parametrized by λ
which geodesic parametrised by s



- If $X^\mu(s, \lambda)$ are the coordinates of geodesics in $\{L\}$, the tangent vector

$$T^\mu = \frac{\partial X^\mu}{\partial \lambda}(s, \lambda)$$

N.B. If λ is \geq (proper time), then $T :=$ velocity

- We can define a "Deviation Vector"

$$X^\mu \equiv \frac{\partial X^\mu}{\partial s}(s, \lambda) \quad \text{to define some sort of velocity between geodesics}$$

- "Relative Acceleration"

$$A^\mu \equiv T^\alpha D_\alpha (T^\beta D_\beta X^\mu)$$

- One can show that

$$A^\mu = R^\mu{}_{\nu\sigma\tau} T^\nu T^\sigma X^\tau$$

Express: The relative acceleration between 2 neighboring geodesics is proportional to the curvature

- In weak field limit

$$g_{00} = 1 + \frac{2\Phi(x, y, z)}{c^2} \quad \leftarrow \text{gravitational potential}$$

Acceleration involves $\frac{d^2\phi}{dx^i dx^j}$ } Tidal Force Tensor Δ_{ij}

In empty space $\Delta^2\Phi = 0 \quad \leftrightarrow \quad \sum_{i=1}^3 \Delta_{ii} = 0$

$$R^{\alpha}{}_{\mu\alpha\beta} \dot{x}^{\mu} \dot{x}^{\beta} = 0$$

Newtonian, empty space

$$\nabla^2 \Phi = 0$$

Newtonian, empty space, introduce Matter

$$\nabla^2 \Phi = \text{const} \cdot \rho$$

→ Here we are trying to obtain the same equation but using tensor

PARENTHESES

1) Volume Element

$d^4x \rightarrow$ is not invariant under coordinate transformation

It transforms like this: $d^4x' = \det \left(\frac{\partial x'^{\mu}}{\partial x^{\nu}} \right) d^4x$

Metric Tensor Transform:

$$g'_{\mu\nu} = \frac{\partial x^{\rho}}{\partial x'^{\mu}} \frac{\partial x^{\sigma}}{\partial x'^{\nu}} g_{\rho\sigma} \implies \det(g'_{\mu\nu}) = \frac{\partial x^{\rho}}{\partial x'^{\mu}} \frac{\partial x^{\sigma}}{\partial x'^{\nu}} \det(g_{\rho\sigma})$$

with this knowledge we conclude that

$$d^4x = dx^1 \wedge \dots \wedge dx^n = \sqrt{\frac{\det[g']}{\det[g]} \frac{\partial(x)}{\partial(x')}} dx^1 \wedge \dots \wedge dx^n = d^4x'$$

e that:

$$\sqrt{\det[g']} \cdot dx^1 \wedge \dots \wedge dx^n = \sqrt{\det[g]} \cdot dx^1 \wedge \dots \wedge dx^n$$

$$\text{Since } dV = \sqrt{\det(g_{\mu\nu})} d^4x \implies dV' = dV$$

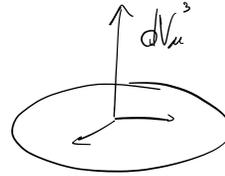
3) GAUSS THEOREM

$$\int_S \mathcal{F} = \int_V \partial \mathcal{F}$$
$$\int d^4x \sqrt{g_4} D_{\mu} A^{\mu} = \int d^3x \sqrt{g_3} D_{\mu} A^{\mu}$$

1) Density

In 3D space a "density" f : $N = \int f dV^3$

$$dV^4 = dx^\mu \underbrace{dV_\mu^3}_{3D} \quad (3+1)D$$

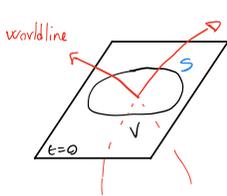


Example 1

Volume element is S-T slice with $t=0$

$$dV_\mu = (dV^3, 0, 0, 0) \longrightarrow dN = \underbrace{f^\mu}_{3D \text{ density}} \underbrace{dV_\mu}_{3D \text{ volume}} \quad \# \text{ particle in 3D volume}$$

Example 2 PARTICLE NUMBER DENSITY

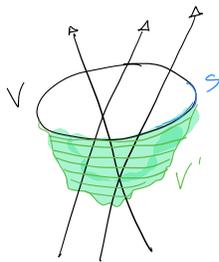


\sim Volume V delimited in a surface S

$$dN = n^\mu dV_\mu \quad \sim \text{number of worldlines (like PARTICLES at } t=0)$$

$$N = \int_V n^\mu dV_\mu$$

Number density vector



PARTICLE is a physics object \Rightarrow Do not Change

Consequence: V is disc, V' is a surface \Rightarrow # particles that cross V , stays cross V'

\Rightarrow If V and V' define an hypervolume H , by Gauss Theorem

$$\int_H \partial_\mu n^\mu d^4H = 0 \quad \forall V, V' \quad \Rightarrow \underline{\underline{\partial_\mu n^\mu = 0}}$$

If we were in Minkowski space $\partial_t n^t = -\vec{\nabla} \cdot \vec{n}$ continuity relation

We could also write $n^\mu(x) = \underbrace{n(x)}_{\text{scalar density}} v^\mu(x)$

\sim In the same way we can think about other quantities

STRESS - ENERGY - MOMENTUM TENSOR

Particle at velocity $V^\mu = \frac{dx^\mu}{d\Sigma} = \frac{dx^\mu}{dt} \frac{dt}{d\Sigma}$ carries a 4-momentum $p^\mu = m\gamma(1, v_i^x, v_i^y, v_i^z)$

Question? Total momentum through a surface S?

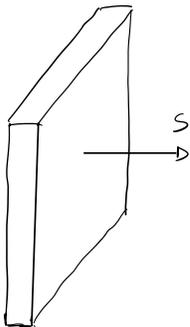
→ To count # particle in a spacetime surface we need a Number-flux 4-vector.

Answer: $P^\mu = \int T^{\mu\nu} dV_\nu \Rightarrow$ Now we need a Tensor

Let's consider an ensemble of particles

$$T^{\mu\nu} \equiv n p^\mu v^\nu = \underbrace{nm}_{\rho(x)} v^\mu v^\nu \quad : \text{Flow of } \mu \text{ momentum going through a unit box of constant } \nu$$

- T^{00} = Energy density (*)
- T^{0i} = Energy density Flow in direction i
- T^{i0} = Momentum Density
- T^{ij} = Flow of i-th momentum in j-th direction



$$dp^i = \underbrace{(\vec{v} \cdot dt)}_{\# \text{ particle leave the box}} \cdot d\vec{S} \cdot n p^i$$

Let $i=j \Rightarrow dp^i > 0 \Rightarrow$ Momentum transferred to surface S

$$\Rightarrow F^i > 0 \Rightarrow \text{pressure } P_{in} > 0$$

$$\Rightarrow T^{ii} > 0 \Rightarrow \text{pressure in the box}$$

Conservation law

Assume that all particles have same velocity travel along geodesics

$$\textcircled{1} \quad \dot{x}^{\mu} = \frac{dV^{\mu}}{d\tau} = \frac{dx^{\mu}}{d\tau} \quad D_{\nu} V^{\mu}(x) = 0$$

\textcircled{2} Particles don't appear/disappear: $D_{\mu}(n(x)V^{\mu}(x)) = 0$

$$D_{\mu} T^{\mu\nu} = D_{\mu}(mn(x)V^{\mu}V^{\nu}) = mV^{\nu} \underbrace{D_{\mu}(n(x)V^{\mu}(x))}_{=0 \text{ (2)}} + mn(x) \underbrace{V^{\mu} D_{\mu} V^{\nu}(x)}_{=0 \text{ (1)}}$$

$$\Rightarrow D_{\mu} T^{\mu\nu} = 0$$

Special Cases

1 IMMOBILE DUST

↳ set of particles w/ worldlines

$$T^{tt} = \rho_0 \rightarrow \text{Rest mass density}$$

2 GENERIC DUST

→ For observer moving along with the dust $V^{\mu} = (1, 0, 0, 0) \Rightarrow T^{\mu\nu} = \rho_0 V^{\mu} V^{\nu}$

$$V = \gamma(1, V_x, V_y, V_z) \Rightarrow T^{\mu\nu} = \rho \cdot \gamma^2 \begin{pmatrix} 1 & V_x & V_y & V_z \\ V_x & V_x^2 & V_x V_y & V_x V_z \\ V_y & V_x V_y & V_y^2 & V_y V_z \\ V_z & V_x V_z & V_y V_z & V_z^2 \end{pmatrix}$$

→ Non zero stress, mass current

3 STATIC MONOENERGETIC GAS

Same V , random orientation

$V^x V^y$ etc = 0 when averaged

$$\langle (V^x)^2 \rangle = \frac{V^2}{3}$$

$$\Rightarrow T^{\mu\nu} = \begin{pmatrix} 1 & & & \\ & \frac{V^2}{3} & & \\ & & \frac{V^2}{3} & \\ 0 & & & \frac{V^2}{3} \end{pmatrix}$$

4| STATIC IDEAL GAS

$V \rightarrow$ Folows statistical distribution

$$T^{\mu\nu} = \begin{pmatrix} \rho & 0 \\ 0 & P & 0 \\ 0 & 0 & P \end{pmatrix}$$

$$V^\mu = (1, 0, 0, 0) \quad \text{and} \quad g^{\mu\nu} = \text{diag}(1, -1, -1, -1)$$

$$T^{\mu\nu} = (\rho + P) V^\mu V^\nu - P g^{\mu\nu} \rightarrow \text{Also valid for observer traversing the gas at some velocity}$$

4.b| Radiation

$$P_R = \frac{\rho_R}{3}$$

$$T^{\mu\nu} = \begin{pmatrix} \rho & & & \\ & \rho/3 & & \\ & & \rho/3 & \\ & & & \rho/3 \end{pmatrix}$$

Gravitation

We are trying to obtain

$$\frac{d^2 \vec{x}}{dt^2} = -\vec{\nabla} \Phi$$

eg: $\Phi = \frac{GM}{r}$ but in CURVED space-time.

Let's define the Newtonian limit

There are various requirements

1) Weak Field $g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}$ \oplus (Metric is a perturbation of flat space)
Keep only terms up to linear in $h_{\mu\nu}$ + derivatives
 \hookrightarrow Small Perturbation

Note: statement about field + coordinates

a) (The metric $^{-+ + +}$)

$$b) g^{\mu\nu} = \eta^{\mu\nu} - h^{\mu\nu}$$

$$(I+A)^{-1} = I^{-1} - I^{-1} A I^{-1} + \mathcal{O}(A^2)$$

2) Small velocities: $\frac{dx^i}{dt} \ll 1 \iff \frac{dx^i}{d\tau} \ll \frac{dt}{d\tau}$ (Moving Slow)

3) Stationary Fields: $\partial_0 g_{\mu\nu} = 0 \iff \partial_0 h_{\mu\nu} = 0$ (Unchanging with time)

Our goal is to go from the equation of motion in General Relativity (Geodesis) to the Newtonian equation of motion

Geodesis

$$\frac{d^2 x^\alpha}{ds^2} + \Gamma_{\mu\nu}^\alpha \frac{dx^\mu}{ds} \frac{dx^\nu}{ds} = 0$$

And Recall

$$\Gamma_{\mu\nu}^\alpha = \frac{1}{2} (\partial_\mu g_{\nu\alpha} + \partial_\nu g_{\mu\alpha} - \partial_\alpha g_{\mu\nu}) g^{\mu\alpha}$$

THE weak field condition we should

$$g^{\mu\nu} = \eta^{\mu\nu} + \mathcal{O}(h)$$

Why? only 1st order in h are allowed and $(\partial(h+h)) \uparrow$
 $g = \eta$

$$\leadsto \partial h_{\mu\nu} = 0$$

$$\text{Weak Field} \implies \Gamma_{\mu\nu}^\alpha = \frac{1}{2} (\partial_\mu h_{\nu\alpha} + \partial_\nu h_{\mu\alpha} - \partial_\alpha h_{\mu\nu}) \eta^{\mu\alpha}$$

Going Back on geodesics, using SMALL VELOCITY

$$\frac{d^2 x^\mu}{d\tau^2} + \Gamma_{00}^\mu \frac{dt}{d\tau} \frac{dt}{d\tau} = 0 \quad \leftarrow \text{The terms } \Gamma_{ij}^\mu \frac{dx^i}{d\tau} \frac{dx^j}{d\tau} \approx 0$$

This means that we only have to compute Γ_{00}^μ

$$\Gamma_{00}^\mu = \frac{1}{2} g^{\mu\nu} \left(\cancel{\partial_0 g_{\nu 0}} + \cancel{\partial_0 g_{\nu 0}} - \partial_\nu g_{00} \right) \Rightarrow \Gamma_{00}^\mu = -\frac{1}{2} \eta^{\mu d} \partial_d h_{00}$$

Static condition

$$= -\frac{1}{2} \eta^{\mu i} \partial_i h_{00} \quad i=1,2,3 \text{ no } 0!$$

So $\Gamma_{00}^0 = 0 \quad \Gamma_{00}^i = -\frac{1}{2} \partial^i h_{00}$

So the geodesics equation

$$\boxed{\frac{d^2 x^\mu}{d\tau^2} + \Gamma_{00}^\mu \frac{dt}{d\tau} \frac{dt}{d\tau} = 0}$$

Splitting Temporal-Spatial Part:

Time $\frac{dt}{d\tau} = 0 \quad \textcircled{1}$

Space $\frac{d^2 x^i}{d\tau^2} = \frac{1}{2} \partial h_{00} \left(\frac{dt}{d\tau} \right)^2 \quad \textcircled{2}$

① Solution: $t = az + b \Rightarrow \frac{dt}{d\tau} = \frac{d^2 x}{dt^2} \left(\frac{dt}{d\tau} \right)^2$

$\rightarrow \frac{dt}{d\tau}$ is constant

Replace in ②, with $\left(\frac{dt}{d\tau} \right)^2$

$$\Rightarrow \boxed{\frac{d^2 x^i}{dt^2} = \frac{1}{2} \partial h_{00}}$$

And we're done because

$$\frac{d^2 \vec{x}}{dt^2} = -\vec{\nabla} \Phi \quad \xrightarrow{\text{Tensorial Way}} \quad \frac{d^2 x^i}{dt^2} = -\partial^i \Phi$$

Which that we can identify $\underline{h_{00} = -2\Phi} \rightarrow \underline{g_{00} = -(1+2\Phi)}$

Newton Gravity can be reproduced by using the metric

$$ds^2 = -(1+2\Phi(\vec{x})) dt^2 + d\vec{x}^2$$

Therefore, we have shown that the curvature of spacetime is indeed sufficient to describe gravity in the Newtonian limit, as long as the metric takes the form

The Einstein Field Equations

Newtonian mechanics $\nabla^2 \Phi = 4\pi G_N \rho$ ①
mass density

Then we discovered $g_{00} = -(1+2\Phi)$ ②

Identity $T_{00} = \rho \Rightarrow \nabla^2 g_{00} = -8\pi G_N T_{00}$

Search Tensor Relation $E_{\mu\nu} = 8\pi G_N T_{\mu\nu}$

What is $E_{\mu\nu}$?

Sensible requirements:

- 1) $E_{\mu\nu}$ is tensor
- 2) Must involve either second derivative or First derivative squared
- 3) $E_{\mu\nu}$ is symmetric
- 4) Covariant Conservation $\Rightarrow D_\mu E^{\mu\nu} = 0$
- 5) In the Newtonian Limit we must have $E_{00} = -\nabla^2 g_{00}$

1)+2) $\Rightarrow R_{\mu\nu} = a R_{\mu\nu} + b g_{\mu\nu} R$ (we are trying with this)

3) also satisfied

4) \Rightarrow Rewrite as $E_{\mu\nu} = a G_{\mu\nu} + c g_{\mu\nu} R$ (Remember $D^\mu g_{\mu\nu} = 0$)

For $D^\mu E_{\mu\nu} = 0$, we must have that $D^\mu (c g_{\mu\nu} R) = c (D_\nu R) = 0$ so we have

2 solutions $\left\{ \begin{array}{l} D_\nu R = 0 \text{ ③} \\ \underline{c = 0} \text{ ④} \end{array} \right.$

③ Physically inconsistent $g^{\mu\nu} E_{\mu\nu} = \underbrace{g^{\mu\nu} a G_{\mu\nu}}_{2R - 2aR} + \underbrace{c g^{\mu\nu} g_{\mu\nu} R}_{= 3^{\mu\nu} = 4} = \underbrace{(4c - 2) R}_{\text{constant if ③}}$
 because $E_{\mu\nu}^{\nu\mu} = \kappa T^{\mu\nu}$

The T should describe generic distribution \rightarrow cannot be constant

So $E_{\mu\nu} = a G_{\mu\nu} \rightarrow$ To Find a go to Newtonian Limit

- 1) Weak Field \rightarrow (change from previous)
keep terms up to linear in h , with $g_{\mu\nu} = \eta + h$
- 2) Time independent metric: $\partial_0 g_{\mu\nu} = \partial_0 h_{\mu\nu} = 0$
- 3) Non relativistic source: $T_{00} = \rho$, $T_{\mu\nu} = 0$ otherwise \rightarrow
 \rightarrow Only need $E_{00} = a G_{00}$

$$G_{00} = R_{00} - \frac{1}{2} g_{00} R$$

at least linear in $h \Rightarrow$ weak field

$$g_{00} \rightarrow \eta_{00} = -1 \rightarrow G_{00} \approx R_{00} + \frac{1}{2} R \quad \textcircled{5}$$

$$T_{ij} = 0 \Rightarrow G_{ij} = 0 \Leftrightarrow R_{ij} = \frac{1}{2} g_{ij} R \Rightarrow R_{ij} = \frac{1}{2} \delta_{ij} R \quad \textcircled{6}$$

just Mink. part

$$\textcircled{5}, \textcircled{6} \Rightarrow R = g^{\mu\nu} R_{\mu\nu} = \eta^{\mu\nu} R_{\mu\nu} = -R_{00} + \frac{3}{2} R \Rightarrow R = 2R_{00}$$

$$\Rightarrow G_{00} = R_{00} + \frac{1}{2} R = 2R_{00}$$

$$R_{00} = R_{0\mu 0}^{\mu}$$

Exercise:

Show that for time independent fields in the weak limit $R_{00} = -\frac{1}{2} \nabla^2 g_{00}$

$$\text{All in all: } G_{00} = 2R_{00} = -\nabla^2 g_{00}$$

$$\text{For (v) to hold } \Rightarrow E_{00} = -\nabla^2 g_{00} \Leftrightarrow a G_{00} = -\nabla^2 g_{00} \Leftrightarrow a = 1$$

$$R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R = 8\pi G_{\mu\nu} T_{\mu\nu}$$

Einstein Equation

\leadsto Tell us how the curvature of space time reacts to the presence of energy momentum.

USED FOR CALCULATE THE METRIC TENSOR \rightarrow CALCULATE CHRISTOFFEL SYMBOLS \rightarrow DETERMINE HOW OBJECTS MOVE

SCHWARZSCHILD SOLUTION

Spherically symmetric Gravitational Field.

no relevant situation to describe the field created by Earth or Sun

In this chapter: Simple case of vacuum solution with perfect SPHERICAL SYMMETRY

Recall Einstein Equation $G_{\mu\nu} = 0$, let's work in Schwarzschild coordinates (t, r, θ, φ)

From movements of particles we can try to know how space is curved and therefore what is the distribution of mass

The Schw coordinates are:

i) (4+3)D

ii) of spherical symmetry

iii) Static

From ii) and iii)

$$\left. \begin{aligned} (t, r, \theta, \varphi) &\longrightarrow (t, r, -\theta, \varphi) &\Rightarrow g'_{\mu\nu} &= g_{\mu\nu} \\ (t, r, \theta, \varphi) &\longrightarrow (t, r, \theta, -\varphi) &\Rightarrow g'_{\mu\nu} &= g_{\mu\nu} \end{aligned} \right\} \text{From ii)}$$
$$(t, r, \theta, \varphi) \longrightarrow (-t, r, \theta, \varphi) \quad \Rightarrow g'_{\mu\nu} = g_{\mu\nu} \quad \left. \vphantom{(t, r, \theta, \varphi)} \right\} \text{From iii)}$$

But $g_{\mu\nu}$ is a (0,2) tensor, so we can write

$$g'_{\mu\nu} = \frac{\partial x^\alpha}{\partial x'^{\mu}} \frac{\partial x^\beta}{\partial x'^{\nu}} g_{\alpha\beta} \quad \text{General Transform. Law}$$

Then as an example

$$\left. \begin{aligned} g'_{\theta\theta} &= \frac{\partial x^\alpha}{\partial(-\theta)} \frac{\partial x^\beta}{\partial(-\theta)} g_{\alpha\beta} = g_{\theta\theta} \\ g'_{\varphi\varphi} &= \frac{\partial x^\alpha}{\partial(-\varphi)} \frac{\partial x^\beta}{\partial(-\varphi)} g_{\alpha\beta} = -g_{\varphi\varphi} \end{aligned} \right\} \begin{aligned} g'_{t\nu} &= -g_{t\nu} \\ \text{But } \underbrace{g'_{\mu\nu} = g_{\mu\nu}}_{\text{Requirement}} &\Rightarrow \underline{g_{\mu\nu} = 0 \quad \forall \mu \neq \nu} \end{aligned}$$

Similarly $g_{2\mu} = 0 \quad \forall \mu \neq 2$ $g_{3\mu} = 0 \quad \forall \mu \neq 3$ $g_{\mu\nu} = 0 \quad \forall \mu \neq \nu$

$\Rightarrow g_{\mu\nu}$ is DIAGONAL (in this coord. system)

iv) Also implies that on each radial line ($\theta, \varphi = \text{const}$), g_{tt} and g_{rr} can only depend on t, r .
 Adding iii) we can conclude that g_{tt}, g_{rr} only depend on r .

\Rightarrow On each hyper surface of $r = \text{const}$ the metric must be the same as the one on a sphere:

$$c^2 d\sigma^2 = A(r) dt^2 - B(r) dr^2 - r^2 \underbrace{(d\theta^2 + \sin^2\theta d\varphi^2)}_{\text{surface of sphere}}$$

Now we want $A(r), B(r)$

Because dt and dr are multiplied by the functions, we don't have neither proper time or proper distance in the line element

Note that

$$G_{\mu\nu} = 0 \Rightarrow g^{\mu\nu} G_{\mu\nu} = 0 \Rightarrow g^{\mu\nu} (R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R) = 0 \Rightarrow R - \frac{1}{2} \cdot 4R = 0$$

$$\Rightarrow -R = 0 \Rightarrow R = 0$$

Called Ricci Flat Manifold

The steps to solve the equation are:

- 1) Christoffel symbols
- 2) Computing R^{μ}_{ν}
- 3) Computing $R_{\mu\nu}$
- 4) Solve $R_{\mu\nu} = 0$

CHRISTOFFEL SYMBOLS

- 2 ways - 1: Brute Force
- 2: More Practical

Consider 3 THINGS:

1) Geodesic Equation

$$\frac{d^2 x^\alpha}{d\tau^2} + \Gamma_{\beta\gamma}^\alpha \frac{dx^\beta}{d\tau} \frac{dx^\gamma}{d\tau} = 0$$

2) Lagrangian

$$\mathcal{L} = \frac{1}{2} g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau}$$

3) Euler-Lagrange Equations

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}^\alpha} - \frac{\partial \mathcal{L}}{\partial x^\alpha} = 0 \quad \text{where } \dot{x}^\alpha \equiv \frac{dx^\alpha}{d\tau}$$

We can derive ① from ② and ③

During this derivation we will encounter

$$\frac{d}{d\tau} \left[g_{\alpha\mu} \dot{x}^\mu \right] - \frac{1}{2} \frac{\partial g_{\mu\nu}}{\partial x^\alpha} \dot{x}^\mu \dot{x}^\nu = 0 \quad \text{④}$$

The method is: start from ④ and try to get a form like

$$\ddot{x}^\alpha + \text{terms} \times \dot{x}^\alpha \dot{x}^\beta = 0$$

Then from such an equation we can directly read the Christoffel Symbols.

We can get:

$$\Gamma_{tr}^t = \Gamma_{rt}^t = \frac{A'}{2A}$$

$$\Gamma_{tt}^r = \frac{A}{2B}$$

$$\Gamma_{rr}^r = \frac{B'}{2B}$$

$$\Gamma_{\theta\theta}^r = -\frac{r}{B}$$

$$\Gamma_{\theta\theta}^r = -\frac{r \sin^2 \theta}{B}$$

$$\Gamma_{rt}^t = \Gamma_{t\theta}^t = \frac{A}{r}$$

$$\Gamma_{\theta\theta}^t = -\sin \theta \cos \theta$$

$$\Gamma_{r\theta}^r = \Gamma_{\theta r}^r = \frac{1}{r}$$

$$\Gamma_{\theta\theta}^r = \Gamma_{\theta\theta}^r = \cot \theta$$

and

$$A' \equiv \frac{dA}{dr} + \text{Remainder} = 0$$

RIEMANN TENSOR

In this case is unnecessary because of what happens to the Ricci Tensor.
It can be directly computed from Christoffel Symbols

Ricci TENSOR

Remember that $R_{\mu\nu} = R^{\lambda}_{\mu\nu\lambda} = \partial_{\mu}\Gamma^{\lambda}_{\nu\lambda} - \partial_{\nu}\Gamma^{\lambda}_{\mu\lambda} + \Gamma^{\lambda}_{\mu\sigma}\Gamma^{\sigma}_{\nu\lambda} - \Gamma^{\lambda}_{\nu\sigma}\Gamma^{\sigma}_{\mu\lambda}$

So we can compute $R_{\mu\nu}$ directly from the metric. We obtain

$$R^t_t = \frac{A''}{2AB} - \frac{A'B'}{4AB^2} - \frac{A'^2}{4A^2B} - \frac{2B^2}{2rB^2}$$

$$R^r_r = \frac{A''}{2AB} - \frac{A'B'}{4AB^2} - \frac{A'^2}{4A^2B} - \frac{2B^2}{2rB^2}$$

$$R^{\theta}_{\theta} = R^{\varphi}_{\varphi} = \frac{A'}{2rAB} - \frac{B'}{2rB^2} - \frac{B-1}{r^2B}$$

SOME $R^{\lambda}_{\lambda} = 0$

$R^t_t - R^r_r - R^{\theta}_{\theta} - R^{\varphi}_{\varphi} = 0$ is independent of A, A', A'' .

All of the terms are 0 because of $R^{\lambda}_{\lambda} = 0$, the subtraction will be 0 too then!

$$R^t_t - R^r_r - R^{\theta}_{\theta} - R^{\varphi}_{\varphi} = 0 \Rightarrow \frac{2B'}{rB^2} + \frac{2(B-1)}{r^2B} = 0$$

$$\frac{dB}{B(B-1)} + \frac{dr}{r} = 0 \Rightarrow \boxed{B(r) = \left(1 + \frac{a}{r}\right)^{-1}} \quad \text{where } a = [L]$$

Now we consider another combination

$$R^t_t - R^r_r = 0 \Rightarrow \frac{A'}{rAB} + \frac{B'}{rB^2} = 0 \Rightarrow \frac{dA}{A} + \frac{dB}{B} = 0 \Rightarrow \boxed{A \cdot B = \text{constant}}$$

Physically this metric is a candidate to describe the space around a static and symmetrical object.

ANY MASSIVE STATIC OBJECT

The boundary condition will be:

$$\left. \begin{array}{l} A(r) \rightarrow c^2 \\ B(r) \rightarrow 1 \end{array} \right\} \text{As } r \rightarrow \infty \Rightarrow \underline{g_{\mu\nu} \rightarrow \eta_{\mu\nu}}$$

Finally

$$A(r) = c^2 \left(1 + \frac{2}{r} \right) \quad B(r) = \frac{1}{1 + \frac{2}{r}}$$

This should also reproduce Newtonian Limit

We can impose that it reduce to $g_{00} = -\left(1 + \frac{2\Phi}{c^2}\right)$ where Φ is the Newtonian Potential
 $\Phi = GM/r$

Putting everything together we find z :

$$ds^2 = -\left(1 - \frac{2GM}{c^2 r}\right) c^2 dt^2 + \left(1 - \frac{2GM}{c^2 r}\right)^{-1} dr^2 + r^2 d\theta^2 + \sin^2\theta d\phi^2$$

SCHWARZSCHILD METRIC

\leadsto for notation $r_s = \frac{2GM}{c^2}$ is the Schwarzschild radius or S-radius

BIRKOFF'S THEOREM

It states that spherical symmetric solutions of the vacuum EFE's is necessarily static

Let's see the behaviour of the Sch-metric:

- i) There is a singularity at $r=0$
- ii) Appears to be a singularity at $r=r_s$
- iii) The t -like component of the metric becomes s -like when choosing r_s value
 \leadsto This messes up with causalities \Rightarrow We lose time variable

Let's see a couple of objects:

- Earth $r_s \approx 1 \text{ cm}$, $r_E \approx 6000 \text{ km}$
 - Sun $r_s \approx 3 \text{ km}$, $r_S \approx 7 \cdot 10^8 \text{ km}$
- } But is valid for EMPTY SPACE

When $r_s \sim r$? White black hole

SCHWARZSCHILD COORDINATES INTERPRETATION

- θ, φ : standard
- t : Fair enough, it's essential time $-\infty < t < +\infty$
- r : Sort of surface area radius.
It has a geometrical interpretation

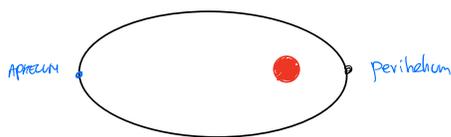
Physics

SCHWARZSCHILD METRIC AT $r \gg r_s$

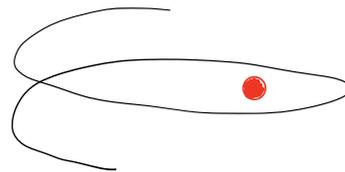
We could compute

- Precession of perihelium of Mercury
- Light deflection by stars

Mercury



Newton



General Relativity

\leadsto General Relativity predict no Newtonian behaviour

Lagrangian

$$\mathcal{L} = g_{\mu\nu} \frac{dx^\mu}{dt} \frac{dx^\nu}{dt}$$

we don't use dt because is 0 for ple...

We saw that

$$\frac{d}{dx} \left(\frac{\partial \mathcal{L}}{\partial \dot{x}^\alpha} \right) - \frac{\partial \mathcal{L}}{\partial x^\alpha} = 0$$

and that the S -metric is

$$ds^2 = - \left(1 - \frac{r_s}{r} \right) c^2 dt^2 + \left(1 - \frac{r_s}{r} \right)^{-1} dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

$$\leadsto \mathcal{L} = - \left(1 - \frac{r_s}{r} \right) c^2 \dot{t}^2 + \left(1 - \frac{r_s}{r} \right)^{-1} \dot{r}^2 + r^2 (\dot{\theta}^2 + \sin^2 \theta \dot{\phi}^2) = \begin{cases} -c^2 & \text{For massive objects} \\ 0 & \text{For photons} \end{cases}$$

For simplicity we will restrict observers to EQUATORS $\Rightarrow \theta = \frac{\pi}{2}$ and \mathcal{L} simplifies to

$$\mathcal{L} = - \left(1 - \frac{r_s}{r} \right) c^2 \dot{t}^2 + \left(1 - \frac{r_s}{r} \right)^{-1} \dot{r}^2 + r^2 \dot{\phi}^2 = \begin{cases} c^2 \\ 0 \end{cases}$$

Note that

- \mathcal{L} does not depend on t
 - \mathcal{L} does not depend on ϕ
 - \mathcal{L} does not depend on θ
- } CYCLIC COORDINATES

From Euler Lagrange Equations we get

$$\left. \begin{aligned} \frac{d}{dx} \left(\frac{\partial \mathcal{L}}{\partial \dot{t}} \right) &= 0 \\ \frac{d}{dx} \left(\frac{\partial \mathcal{L}}{\partial \dot{\phi}} \right) &= 0 \end{aligned} \right\} \begin{aligned} &\text{These quantities are conserved in geodesics} \\ &\text{Conserved quantities are energy and angular momentum} \end{aligned}$$

$$\frac{d}{dx} \left(\frac{\partial \mathcal{L}}{\partial \dot{\theta}} \right) = 0 \Rightarrow \text{Trivial}$$

From the NON-TRIVIAL EL equation consequence we get

$$\left[\left(1 - \frac{\epsilon}{r}\right) \dot{t} = \alpha, \quad r \dot{e} \right] \text{ where } \alpha, \epsilon \text{ are constant}$$

Letely we can always write $\frac{dr}{dt} = \frac{dr}{de} \frac{de}{dt} \Rightarrow \dot{r} = \frac{dr}{de} \dot{e}$

We see

$$L = -\left(1 - \frac{r_s}{r}\right) c^2 \dot{t}^2 + \left(1 - \frac{r_s}{r}\right)^{-1} \dot{r}^2 + r^2 \dot{\varphi}^2 = \begin{cases} < c^2 & \text{massive particles} \\ 0 & \text{photons} \end{cases} \quad \textcircled{A}$$

And conservation laws:

$$\textcircled{B} \quad \left(1 - \frac{r_s}{r}\right) \dot{t} = \delta$$

$$\textcircled{C} \quad r^2 \dot{\varphi} = S$$

$$\textcircled{D} \quad \dot{r} = \frac{dr}{d\varphi} \dot{\varphi}$$

$$\textcircled{A}, \textcircled{B}, \textcircled{C}, \textcircled{D} \quad \Rightarrow \quad \left(\frac{dr}{d\varphi}\right)^2 = \frac{c^2 \delta^2 r^4}{S^2} - r^2 + r_s r \quad \delta = \left(1 - \frac{r_s}{r}\right) \dot{t}$$

DIFFERENTIAL EQUATION

$$S = r^2 \dot{\varphi}$$

To solve \Rightarrow change of variable $u = \frac{1}{r}$

$$\Rightarrow \quad \left(\frac{du}{d\varphi}\right)^2 = r_s u^3 - u^2 + \beta \quad \textcircled{E} \quad \beta = \frac{c^2 \delta^2}{S^2}$$

\Uparrow We will get $r(\varphi)$ because we want to see how photons behaves in gravitational field \Downarrow

Formal Solution: $\varphi - \varphi_0 = \int_{u_0}^u \frac{du}{\sqrt{r_s u^3 - u^2 + \beta}}$ where φ_0, u_0 : points on the trajectory

We know then

$$\frac{du}{d\varphi} = 0 \quad \text{at perihelion, aphelion}$$

So at PE/APH $\Rightarrow \frac{du}{d\varphi} = 0 \Rightarrow r_s u_{\pm}^3 - u_{\pm}^2 + \beta = 0 \Rightarrow \beta = u_{\pm}^2 - r_s u_{\pm}^3$

\hookrightarrow When we hit PE/APH u_{\pm} is a root of the polynomial

Now we can rewrite \textcircled{E} as

$$\left(\frac{du}{d\varphi}\right)^2 = (u_{\pm} - u) [Au^2 + Bu + c] \quad A, B, C \text{ can be compute by matching the original polynomial}$$

So doing that is

$$\left(\frac{dU}{d\varphi}\right)^2 = (U_{\perp} - U) \left[(U_{\perp} + U) - r_s (U_{\perp}^2 + U_{\perp}U + U^2) \right]$$

Reproduce $\rightarrow r_s U^3 - U^2 + \beta$, but expanded

Replacing in our integral

$$\int_{U_0}^U \frac{1}{\sqrt{(U_{\perp} - U) \left[(U_{\perp} + U) - r_s (U_{\perp}^2 + U_{\perp}U + U^2) \right]}} dU$$

We are interested in $r \gg r_s$, so we Taylor expand wrt $z \equiv \frac{r_s}{r} = r_s U$

$$\varphi - \varphi_0 = \int_{U_0}^U \frac{dU}{\sqrt{U_{\perp}^2 - U^2}} \left[1 + \frac{1}{z} r_s \left(\frac{U^2 + U U_{\perp} + U_{\perp}^2}{U + U_{\perp}} \right) + \mathcal{O}(z^2) \right]$$

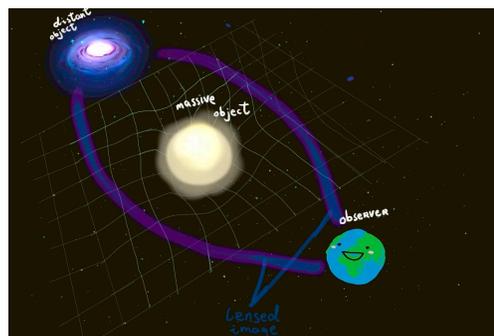
Integrate by switching to q , defined through $U = U_{\perp} \frac{1 - q^2}{1 + q^2}$

As $-1 \leq q \leq +1$, passing through 0, $\Rightarrow U$ starts from 0 then come back to 0, passing through U_{\perp}

$$\Rightarrow \Delta\varphi = \underbrace{\pi}_{\text{Newton}} + \underbrace{2r_s U_{\perp}}_{\text{Leading corrections } \Delta\varphi_1}$$



Consequence: GRAVITATIONAL LENSING



S metric appear to have 2 singularities - $r=0$
 - $r=r_s$

- $r=0$ is indeed singularity but not "naked"

At $r=r_s$, the t -variable becomes SPACE-LIKE

It's NOT A PHYSICAL TRUE SINGULARITY
 IT'S A COORDINATE SINGULARITY

Consider radially ($\theta = \varphi = \text{const}$) photons

2 solutions

$$c^2 \left(1 - \frac{r_s}{r}\right) dt^2 - \frac{dr^2}{\left(1 - \frac{r_s}{r}\right)} = 0 \quad \left\{ \begin{array}{l} c dt = \frac{dr}{1 - r_s/r} \\ -c dt = \frac{dr}{1 - r_s/r} \end{array} \right.$$

OUTGOING PHOTON

INCOMING PHOTON

$$\Rightarrow \begin{cases} ct = r + r_s \ln\left(\frac{r}{r_s} - 1\right) + C & \text{OUTGOING} \\ -ct = r + r_s \ln\left(\frac{r}{r_s} - 1\right) + D & \text{INCOMING} \end{cases}$$

Kruskal - Szekeres COORDINATES:

- $UV = e^{\frac{(t+r)}{2r_s}} = e^{\frac{r}{r_s}} \left(\frac{r}{r_s} - 1\right)$
- $\pm \frac{V}{U} = e^{\frac{(t-r)}{2r_s}} = e^{\frac{ct}{r_s}} \quad \rightarrow \quad +: r > r_s \quad -: r < r_s$

Let's see how metric transform if we perform this coordinate change

$$\begin{aligned} d(VU) &= dVU + VdU = VU \left(\frac{dV}{V} + \frac{dU}{U} \right) = e^{\frac{r}{r_s}} \left[\frac{1}{r_s} + \frac{1}{r} \left(\frac{r}{r_s} - 1 \right) \right] dr \\ &= \frac{VU}{\frac{r}{r_s} - 1} \frac{dr}{\frac{r_s}{r}} = \frac{VU}{r_s \left(1 - \frac{r_s}{r}\right)} \end{aligned}$$

$$d\left(\frac{V}{U}\right) = \dots = \frac{V}{U} \left(\frac{dV}{V} - \frac{dU}{U} \right) = \dots = \left(\frac{V}{U}\right) \frac{c dt}{r_s}$$

Finally

$$\frac{dV}{V} + \frac{dU}{U} = \frac{dr}{r_s \left(1 - \frac{r_s}{r}\right)} \quad \frac{dV}{V} - \frac{dU}{U} = \frac{c dt}{r_s}$$

Then plug them back into the metric

$$ds^2 = \left(1 - \frac{r_s}{r}\right) \left[-c^2 dt^2 + \frac{dr^2}{\left(1 - \frac{r_s}{r}\right)^2} \right] = \left(1 - \frac{r_s}{r}\right) r_s^2 \left[-\left(\frac{dV}{V} - \frac{dU}{U}\right)^2 + \left(\frac{dV}{V} + \frac{dU}{U}\right)^2 \right] \Rightarrow$$

$$ds^2 = -\frac{4r_s^3}{r} e^{-r/r_s} dV dU$$

$$g_{\mu\nu} \rightarrow \begin{bmatrix} +\frac{4r_s^3}{r} e^{-\frac{r}{r_s}} & 0 & 0 & 0 \\ 0 & -\frac{4r_s^3}{r} e^{-\frac{r}{r_s}} & 0 & 0 \\ 0 & 0 & -r^2 & 0 \\ 0 & 0 & 0 & -r^2(\sin\theta)^2 \end{bmatrix}$$

No more singularity at $r=r_s$

Remark

• For given U, V I can compute r

$$VU = \left(\frac{r}{r_s} - 1\right) e^{-\frac{r}{r_s}}$$

Plot

What do the ScO coordinates look like in U, V plane?

1) $V=0, U=0 \Rightarrow VU=0$

$$\rightarrow e^{-\frac{r}{r_s}} \left(\frac{r}{r_s} - 1\right) = 0$$

$$r = r_s$$

↳ Along both axes we are in $r=r_s$

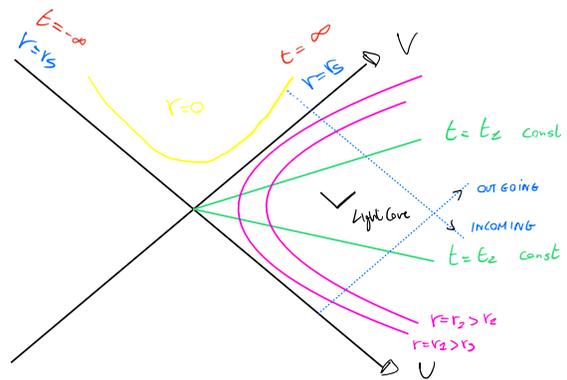
2) $V=0 \Rightarrow \frac{V}{U} = 0 \Rightarrow e^{\frac{ct}{r_s}} = 0$
 $\rightarrow t = -\infty$

$U=0 \Rightarrow \frac{V}{U} = \infty \Rightarrow e^{\frac{ct}{r_s}} = \infty$
 $\rightarrow t = \infty$

3) $t = \text{const} \Rightarrow \frac{V}{U} = \text{const} \Rightarrow \underline{V = \text{const} \times U}$ *time const*

4) $r = \text{const} \Rightarrow r > r_s \Rightarrow \underline{VU = \text{const}}$ in 1st quadrant

5) $r=0 \Rightarrow \underline{VU = -1}$



Observer in Radial Free-Fall in Schwarzschild metric:

$$\text{Lagrangian: } \mathcal{L} = c^2 \left(1 - \frac{r_s}{r}\right) \dot{t}^2 - \left(1 - \frac{r_s}{r}\right)^{-1} \dot{r}^2 = c^2 \quad \textcircled{1}$$

From previous problem: $\left(1 - \frac{r_s}{r}\right) \dot{t} = \gamma \quad \textcircled{2}$ with $\gamma = \sqrt{1 + \frac{\dot{r}^2}{c^2} - \frac{r_s}{r}}$ \dot{t} : gctic
choose $\gamma = 1 \rightarrow (\dot{r} = 0 \text{ et } \infty)$

From $\textcircled{1}$ and $\textcircled{2}$

$$\dot{r}^2 = \frac{r_s c^2}{r} \quad \dot{t} = \frac{1}{1 - \frac{r_s}{r}}$$

Introduce x : $r = r_s x^2 \Rightarrow dr = 2r_s x dx$

$$\textcircled{3} \Rightarrow 2r_s x^2 dx = c dz \Rightarrow cz = \frac{2}{3} r_s x^3 \quad (\text{For } \gamma = 1)$$

Assuming a static observer at $r > r_s$

$$\textcircled{4} \Rightarrow dt = \frac{dz}{1 - \frac{r_s}{r}}$$

Substituting in the results for dz , r we obtain

$$c dt = \frac{2r_s x^2 dx}{x^2 - 1} \Rightarrow ct = r_s \left[\frac{2}{3} x^3 + 2x + \ln \left(\frac{x-1}{x+1} \right) \right]$$

$$\text{As } x \rightarrow 1 \quad \left(\rightarrow cz \rightarrow -\frac{2}{3} r_s, r \rightarrow r_s \right)$$

Cosmological Principle: Universe is Homogeneous \oplus Isotropic

We want to build an average Metric for the universe

- 1) Copernican Principle: The universe should look the same at any spatial Point (Homogeneity)
- 2) Isotropy: The space looks no matter in what direction are you looking at.

FRIEDMAN - LEMAITRE - ROBERTSON - WALKER METRIC (FLRW)

1) Isotropic Coordinates (t, x, y, z)

Impose That

1) The symmetry has origin at $x=y=z=0$

2) Line element of 3-space: $dl^2 = g(t, \sqrt{x^2+y^2+z^2})$

NOT THE PROPER DISTANCE FROM THE ORIGIN

Move to spherical coordinates (t, r, θ, φ)

$$\begin{cases} x = r \sin \theta \cos \varphi \\ y = r \sin \theta \sin \varphi \\ z = r \cos \theta \end{cases} \gg dl^2 = g(t, r) (dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\varphi^2)$$

• Demand $g_{\mu\nu}$ invariant under $\begin{matrix} \theta \rightarrow -\theta \\ \varphi \rightarrow -\varphi \end{matrix} \Rightarrow g_{\theta\theta} = g_{\varphi\varphi} = 0$

$$\leadsto ds^2 = f(t, r) c^2 dt^2 + g(t, r) dr^2 + h(t, r) dt dr + g(t, r) r^2 (d\theta^2 + \sin^2 \theta d\varphi^2)$$

f, g, h unknown functions

$\Rightarrow h(t, r) dt dr \rightarrow$ annoying but **ERGASBAR**

Why? Consider example

$$ds^2 = -A(r) dt^2 + B(r) dr^2 + 2C(r) dt dr$$

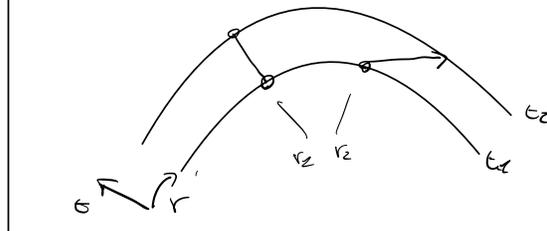
$$\text{Introduce } T(t, r) \equiv t + \psi(r) \Rightarrow dT^2 = dt^2 + \psi'^2 dr^2 + 2\psi' dt dr \quad (\psi' \equiv \frac{d\psi}{dr})$$

$\rightarrow C$ can be eliminated by choosing $\psi: \frac{d\psi(r)}{dr} = -\frac{C}{A}$

\leadsto Basically we can choose $C(r) = 0$

So as the example we can choose $h(r,t) = 0$

Physical Explanation



2 observer at 2 different radii
measures 2 different time \Rightarrow AGAINST
HOMOGENEOUS

Let's rewrite the metric with $h=0$:

$$ds^2 = -f(t,r)c^2 dt^2 + g(t,r) [dr^2 + r^2 d\theta^2 + r^2 \sin^2\theta d\varphi^2]$$

OBSERVE THAT

Every static observer same t -measurement $\Rightarrow f = f(t) \Rightarrow$ does not depend on r
We can perform a coordinate transformation: $dt \rightarrow dt = \sqrt{f} dt$
"synchronization"

OBSERVE THAT

From homogeneity: $g(t,r) = a^2(t) h(r)$

$$ds^2 = -c^2 dt^2 + a^2(t) h(r) [dr^2 + r^2 d\theta^2 + r^2 \sin^2\theta d\varphi^2]$$

We can perform coordinate transformation $\tilde{r}^2 = h(r) r^2$

$$\Rightarrow ds^2 = -c^2 dt^2 + a^2(t) W(\tilde{r}) d\tilde{r}^2 + a^2(t) \tilde{r}^2 [d\theta^2 + \sin^2\theta d\varphi^2]$$

Spzital Part - Same generic form \Rightarrow 3-metric

Recycle results From Schwarzschild ($A=0$)

For spzital part

$$R_3 = \frac{2W'}{2rw^2} + \frac{W'}{rw^2} + \frac{2(W-1)}{r^2w}$$

Homogeneity $\Rightarrow R_3 = \text{const}$ in space = $6K$ $K \in \mathbb{R}$

$$W(\tilde{r}) = \frac{1}{1 - K\tilde{r}^2}$$

$$ds^2 = -c^2 dt^2 + \tilde{a}(t) \left[\frac{dr^2}{1-kr^2} + r^2 d\theta^2 + r^2 \sin^2\theta d\phi^2 \right]$$

FLRW Metric

Comments

- no $K=0, \pm 1$
- 0 : closed, finite volume
 - +1 : flat, infinite volume
 - -1 : hyperboloid

no Ricci Scalar

$$R = 6 \left[\frac{\ddot{a}}{a^2} + \frac{\dot{a}^2}{a^2} + \frac{K}{a^2} \right]$$

S-T flat if $K=0$ AND $\dot{a}=\text{const}$

$\dot{a}=0$ is singularity
 $\dot{a} \rightarrow 0$ scale factor

- $K=+1$: $r = \frac{1}{\sqrt{K}} \sin \chi$

$$dl^2 = d\chi^2 + \sin^2 \chi (d\theta^2 + \sin^2 \theta d\phi^2)$$

- $K=0$: $r = \chi$

$$dl^2 = d\chi^2 + \chi^2 (\dots)$$

- $K=-1$: $r = \frac{1}{\sqrt{-K}} \sinh \chi$

$$dl^2 = d\chi^2 + \sinh^2 \chi (\dots)$$

no It's possible to show that any worldline of $\chi, \theta, \phi = \text{const}$ is a geodesic and $t \propto \tau$

no For an observer at rest in the comoving frame :

1) ∇ local momentum flow

2) Local stress : isotropic

no Observer at the coordinate origin — Observer at constant χ

distance at: $a(t)\chi$ distance depends on time

no Cosmological Redshift

Fundamental Observer A at $x=0$

Light pulse emission at t_A



Fundamental observer at x_B receives pulse at t_B

$$dt^2 - a^2 dx^2 = 0 \quad \Rightarrow \quad \int_{t_A}^{t_B} dt/a = x_B$$

At $t_A + \Delta t_A$, another pulse, received at $t_B + \Delta t_B$ | $x_A = \text{chore}$ $x_B = \text{const}$

$$\Delta \int_{t_A}^{t_B} \frac{dt}{a(t)} = \frac{\Delta t_B}{a(t_B)} - \frac{\Delta t_A}{a(t_A)} = 0$$

Δt_A : period of photon

Expansion:

GRAVITATIONAL WAVES

Electromagnetism Review

Lorentz: $m\vec{x} = e\vec{E} + \frac{e}{c} \vec{x} \times \vec{B}$

Maxwell: $\vec{\nabla} \cdot \vec{E} = 4\pi\rho$

$\vec{\nabla} \cdot \vec{B} = 0$

$\vec{\nabla} \times \vec{E} = -\frac{1}{c} \frac{\partial \vec{B}}{\partial t}$

$\vec{\nabla} \times \vec{B} = \frac{4\pi}{c} \vec{J} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$

$\vec{A}: \vec{B} = \vec{\nabla} \times \vec{A}$

$\phi: \vec{E} + \frac{1}{c} \frac{\partial \vec{A}}{\partial t} = -\nabla\phi$

They can manifest from an action

$$S = S_n + S_{int} + S_{EM}$$

↳ Free Particle ↳ Interaction Term ↳ electromagn.

$$S_n = -mc \int_{\uparrow} \sqrt{-ds^2}$$

$$S_{int} = \frac{e}{c} \int_{\uparrow} A_\mu dx^\mu = \frac{1}{c^2} \int_{\mathcal{O}} J^\mu A_\mu d^4x$$

$$S_{EM} = -\frac{1}{16\pi c} \int_{\mathcal{O}} F^{\mu\nu} F_{\mu\nu} d^4x$$

Defining:

$$F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu$$

$$A^\mu = (\phi, \vec{A}) \rightarrow \text{scalar}$$

$$J^\mu = (\rho c, \vec{j})$$

$\rho \rightarrow$ charge density

Inhomogeneous M-E: $\partial_\mu F^{\mu\nu} = -\frac{4\pi}{c} J^\nu$

Invariant under $A_\mu(x) \rightarrow A'_\mu(x) = A_\mu(x) + \partial_\mu \Lambda(x)$

GAUGE INVARIANCE

Λ is a generic function

Ex: Choose $A_\mu: \partial_\mu A^\mu = 0$ "Lorentz Gauge" $>$ Always Possible

Why all of this? In GR the same things happen because the Einst. Equation works in EVERY COORDINATE SYSTEM

→ The physics remains unchanged

Linearized Gravity

Same idea as Newtonian limit

$$g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}$$

↳ Perturbation

Reminder: $g^{\mu\nu} = \eta^{\mu\nu} - h^{\mu\nu}$

↳ We will drop order of h^2 , ∂h^2 Drop

Proof: $g^{\mu\nu} = \eta^{\mu\nu} + H^{\mu\nu}$

$$g_{\mu\nu} g^{\nu\rho} = (\eta_{\mu\nu} + h_{\mu\nu})(\eta^{\nu\rho} + H^{\nu\rho}) = \delta_{\mu}^{\rho} + \eta_{\mu\nu} H^{\nu\rho} + h_{\mu\nu} \eta^{\nu\rho} + \mathcal{O}(hH)$$

$$\rightarrow H_{\mu}^{\rho} = -h_{\mu}^{\rho} = -h^{\mu\rho}$$

Remarks:

- Raise or lower indices with $\eta^{\mu\nu}/\eta_{\mu\nu}$ (in linearised gravity)

- Summary: $g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}$

$$g^{\mu\nu} = \eta^{\mu\nu} - h^{\mu\nu}$$

$$g^{\mu}_{\nu} = \delta^{\mu}_{\nu} (= \eta^{\mu}_{\nu}) \quad \text{where } h^{\alpha}_{\nu} = \eta^{\alpha\mu} h_{\mu\nu}$$

$$h^{\mu\nu} = \eta^{\nu\alpha} h^{\mu}_{\alpha}$$

so that $g_{\mu\nu} g^{\nu\rho} = \delta_{\mu}^{\rho}$

- $h_{\mu\nu}$ is TENSOR only under Minkowsky

Einstein Field Equation in Linearized Gravity

Christoffel Symbol

By definition $\Gamma_{\sigma\gamma}^{\alpha} = \frac{1}{2} g^{\alpha\mu} (\partial_{\sigma} g_{\mu\gamma} + \partial_{\gamma} g_{\mu\sigma} - \partial_{\mu} g_{\sigma\gamma})$

• We require $O(h) \rightarrow g^{\alpha\mu} = \eta^{\alpha\mu}$

$\leadsto \Gamma_{\sigma\gamma}^{\alpha} = \frac{1}{2} \eta^{\alpha\mu} (\partial_{\sigma} h_{\mu\gamma} + \partial_{\gamma} h_{\mu\sigma} - \partial_{\mu} h_{\sigma\gamma})$

Riemann Tensor

By definition $R_{\mu\sigma\nu}^{\alpha} = \partial_{\sigma} \Gamma_{\mu\nu}^{\alpha} - \partial_{\nu} \Gamma_{\mu\sigma}^{\alpha} + \Gamma_{\mu\nu}^{\beta} \Gamma_{\beta\sigma}^{\alpha} - \Gamma_{\mu\sigma}^{\beta} \Gamma_{\beta\nu}^{\alpha}$
 $O(h^2)$

$\leadsto R_{\mu\sigma\nu}^{\alpha} \simeq \partial_{\sigma} \Gamma_{\mu\nu}^{\alpha} - \partial_{\nu} \Gamma_{\mu\sigma}^{\alpha}$

$\hat{=} \frac{1}{2} \eta^{\alpha\lambda} (\partial_{\sigma} h_{\lambda\nu} + \partial_{\nu} h_{\lambda\sigma} - \partial_{\lambda} h_{\sigma\nu}) -$

$-\frac{1}{2} \eta^{\alpha\lambda} (\partial_{\nu} h_{\lambda\sigma} + \partial_{\sigma} h_{\lambda\nu} - \partial_{\lambda} h_{\sigma\nu})$
 (same)

$\times \eta_{\rho\alpha} \left(\leadsto R_{\mu\sigma\nu\rho} \simeq \frac{1}{2} \eta^{\alpha\lambda} (\partial_{\sigma} \partial_{\lambda} h_{\nu\rho} - \partial_{\sigma} \partial_{\lambda} h_{\rho\nu} - \partial_{\nu} \partial_{\lambda} h_{\sigma\rho} - \partial_{\nu} \partial_{\lambda} h_{\rho\sigma}) \Rightarrow O(h) \right)$

$\leadsto R_{\lambda\mu\sigma\nu} \simeq \frac{1}{2} (\partial_{\sigma} \partial_{\lambda} h_{\nu\mu} - \partial_{\sigma} \partial_{\lambda} h_{\mu\nu} - \partial_{\nu} \partial_{\lambda} h_{\sigma\mu} - \partial_{\nu} \partial_{\lambda} h_{\mu\sigma}) \Rightarrow O(h)$

Remark: • These tensors satisfy Bianchi identities

Ricci Tensor

By definition $R_{\mu\nu} = g^{\sigma\tau} R_{\lambda\mu\sigma\nu} \simeq \eta^{\sigma\tau} R_{\lambda\mu\sigma\nu}$
 $\simeq \eta^{\sigma\tau} O(h)$

$\Rightarrow R_{\mu\nu} = \frac{1}{2} (\partial_{\mu} \partial^{\lambda} h_{\lambda\nu} + \partial_{\nu} \partial^{\lambda} h_{\lambda\mu} - \square h_{\mu\nu} - \partial_{\mu} \partial_{\nu} h)$
 $\downarrow \eta^{\sigma\lambda} \partial_{\lambda}$
 $\rightarrow h = \eta^{\lambda\mu} h_{\lambda\mu}$
 $\rightarrow \square = \eta^{\mu\nu} \partial_{\mu} \partial_{\nu}$

Rici Scalar

By definition $R = g^{\mu\nu} R_{\mu\nu} \simeq \eta^{\mu\nu} R_{\mu\nu} = \frac{1}{2} (\partial^\nu \partial^\alpha h_{\nu\alpha} + \partial^\alpha \partial^\nu h_{\mu\alpha} - \square h - \square h)$

$$\Rightarrow R = \partial^\mu \partial^\nu h_{\mu\nu} - \square h$$

Einstein Equation

By definition $R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R = 8\pi G_n T_{\mu\nu}$

$$\sim \frac{1}{2} (\partial_\alpha \partial^\alpha h_{\nu\alpha} + \partial_\nu \partial^\alpha h_{\alpha\mu} - \square h_{\mu\nu} - \partial_\mu \partial_\nu h) - \frac{1}{2} \eta_{\mu\nu} (\partial^\sigma \partial^\beta h_{\sigma\beta} - \square h) = 8\pi G_n T_{\mu\nu}$$

Trace Reversed perturbation

$$\hat{h}_{\mu\nu} = h_{\mu\nu} - \frac{1}{2} \eta_{\mu\nu} h \quad \Downarrow$$

Computing the TRACE $\hat{h} = \eta^{\mu\nu} \hat{h}_{\mu\nu} = h - 2h = \underline{\underline{\hat{h} = -h}}$

So we can invert $\hat{h}_{\mu\nu} = h_{\mu\nu} - \frac{1}{2} \eta_{\mu\nu} \hat{h}$

Substitute in Einstein Equation:

$$\frac{1}{2} \left[\partial_\mu \partial^\alpha \hat{h}_{\nu\alpha} - \frac{1}{2} \eta_{\nu\alpha} \partial_\mu \partial^\alpha \hat{h} + \partial_\nu \partial^\alpha \hat{h}_{\alpha\mu} - \frac{1}{2} \eta_{\alpha\mu} \partial_\nu \partial^\alpha \hat{h} - \square \hat{h}_{\mu\nu} + \right. \\ \left. + \frac{1}{2} \eta_{\mu\nu} \square \hat{h} + \partial_\mu \partial_\nu \hat{h} \right] - \frac{1}{2} \eta_{\mu\nu} \left(\partial^\sigma \partial^\beta \hat{h}_{\sigma\beta} - \frac{1}{2} \eta_{\sigma\beta} \partial^\sigma \partial^\beta \hat{h} + \square \hat{h} \right) = 8\pi G_n T_{\mu\nu}$$

\Rightarrow Einstein Eqs:

$$\partial_\mu \partial^\alpha \hat{h}_{\nu\alpha} + \partial_\nu \partial^\alpha \hat{h}_{\alpha\mu} - \square \hat{h}_{\mu\nu} - \eta_{\mu\nu} \partial^\sigma \partial^\beta \hat{h}_{\sigma\beta} = 16\pi G_n T_{\mu\nu}$$

Harmonic Gauge

Interestingly, linearized gravity does by no means, uniquely specify the perturbation $h_{\mu\nu}$.

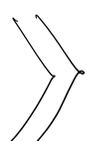
→ The freedom to perform an infinitesimal coordinate transformation $x^\alpha \rightarrow x'^\alpha = x^\alpha + \xi(x^\alpha)$ give rise to AN INVARIANCE UNDER GAUGE TRANSFORMATION

$\partial_\mu \tilde{h}^{\mu\nu} = 0$ Harmonic / Hilbert / De Donder gauge
Choice

→ I go in the coordinate in which the $\tilde{h}^{\mu\nu}$ has THAT FORM

We get

$$\square \tilde{h}_{\mu\nu} = -16\pi G_N T_{\mu\nu}$$



Thus, \tilde{h}_{ab} represents a quantity that propagates as a wave at the vacuum speed of light, on a flat Minkowski background, and which is sourced by the energy-momentum tensor T_{ab} of matter; in other words, \tilde{h}_{ab} is a *gravitational wave*.



⇒ $\square \tilde{h}_{\mu\nu} = -16\pi G_N T_{\mu\nu} \rightarrow$ Brings us to harmonic gauge

N.B. If we are in the harmonic gauge \textcircled{A} with $\partial_\mu \tilde{h}^{\mu\nu} = 0 \Rightarrow$ We stay in harmonic gauge

→ The formal solution of E. Eq

$$\tilde{h}_{\mu\nu}(t, \vec{x}) = 4G_N \int_{\text{over Flat space}} d^3\vec{x}' \frac{T_{\mu\nu}(t - |\vec{x} - \vec{x}'|, \vec{x}')}{|\vec{x} - \vec{x}'|}$$

Transverse - Traceless (TT) gauge

$\tilde{h}_{\mu\nu}$: A priori: 10 independent components

$\tilde{h}_{\mu\nu} \rightarrow$ symmetric

Harmonic Gauge condition $\Rightarrow \tilde{h}_{\mu\nu} \rightarrow$ 6 ind. components

Which means that the harmonic gauge condition does not uniquely specify the metric perturbation $h_{\mu\nu}$.

INDEED any gauge transformation whose generator ξ^α satisfies $\square \xi^\alpha = 0 \rightarrow$ Does preserve the GAUGE CONDITION

To uniquely specify the metric perturbation, 4 additional constraints must be IMPOSED

$\Rightarrow \tilde{h} \rightarrow$ 2 independent (physical) components

In practice

1) Choose ξ^0 : $\hat{h} = 0$ (i.e. $\hat{h}_{\mu\nu} \rightarrow$ traceless)

2) Choose ξ^i 's: $h_{0i} = 0 \Rightarrow \partial^\alpha \hat{h}_{\mu\nu} = 0 \Rightarrow \partial^\alpha h_{\mu\nu} = 0 \Rightarrow \partial^0 h_{00} = 0$

\Rightarrow h_{00} is t -independent

\hookrightarrow Newtonian independent

$$\Rightarrow \boxed{h_{0\alpha} = 0 \quad h = 0 \quad \partial^i h_{ij} = 0}$$

Notation: We write e.g. $\tilde{h}_{\mu\nu}^{\text{TT}}$

N.B. In vacuum, $\square \tilde{h}_{\mu\nu} = 0$ or choose $\square \xi_\mu = 0 \rightarrow$ TT gauge always possible in vacuum

\neq

With matter $\square \tilde{h}_{\mu\nu} \neq 0$
 \rightarrow Not always possible to go to TT gauge

GRAVITATIONAL WAVES: Propagation in vacuum

$$\square \hat{h}_{\mu\nu}^{\text{TT}} = 0 \quad \rightarrow \text{It's a Wave equation}$$

Assuming $h_{\rho\mu}^{\text{TT}} = 0 \Rightarrow$ Plane wave solution is

$$\underline{h_{bc}^{\text{TT}} = \epsilon_{bc} e^{ik^\alpha x_\alpha}}$$

where $\bullet K^\alpha = (\omega, \vec{k})$, $\omega = |\vec{k}|$ (Angular Frequency) of Gr. Wave.

$\bullet \epsilon_{bc}$ = pol. tens

$\bullet \omega^2 = |\vec{k}|^2 \rightarrow$ Disp. Relation

For propagation in z -direction

$$h_{\alpha\beta}^{\text{TT}} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & h_+ & h_\times & 0 \\ 0 & h_\times & -h_+ & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \cos[\omega(t - z/c)]$$

Where h_+, h_\times : amplitudes of polarizations modes

We can also write:

$$h_{bc}^{\text{TT}} = h_+ \epsilon_{bc}^+ \cos[\omega(t - z)] + h_\times \epsilon_{bc}^\times \cos[\omega(t - z)]$$

$$\text{using } \epsilon_{bc}^+ = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\epsilon_{bc}^\times = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Then the LINE ELEMENT

$$ds^2 = -c^2 dt^2 + (1 + h_+ \cos \varphi) dx^2 + (1 - h_+ \cos \varphi) dy^2 + 2h_\times \cos \varphi dx dy + dz^2$$

$$\rightarrow \varphi \equiv \omega(t - z/c)$$

1) Single particle in path of GR

Free Particle : $\ddot{x}^\mu + \Gamma_{\rho\sigma}^\mu \frac{dx^\rho}{d\tau} \frac{dx^\sigma}{d\tau} = 0$

Particle at rest at $\tau=0 \rightarrow$ At $\tau=0 : \frac{dx^\mu}{d\tau} = 0$

$\Rightarrow \ddot{x}^\mu + \Gamma_{00}^\mu = 0 \Rightarrow \ddot{x}^\mu = -\Gamma_{00}^\mu = \frac{1}{2} \eta^{\mu\alpha} (\partial_0 h_{0\alpha} + \partial_0 h_{\alpha 0} - \partial_\alpha h_{00})$

In TT-gauge : $h_{0\alpha} = 0 \Rightarrow \ddot{x}^\mu = 0$ (at $\tau=0$) \Rightarrow Particle at Rest

But Rest with respect to his coordinate system

What if we consider the proper distance between 2 particles?

2) Two particles at $(x_0, 0, 0), (-x_0, 0, 0)$

How does the proper distance evolve?

$$\Delta l = \int_{-x_0}^{x_0} (|ds|)^{1/2} = \int_{-x_0}^{x_0} \sqrt{|g_{xx} dx^x dx^x|}$$

$$= \int_{-x_0}^{x_0} \sqrt{1 + h_{xx}} dx' \simeq L_0 \left[1 + \frac{1}{2} h_{xx} \cos(\omega t) \right] \quad L_0 = 2x_0$$

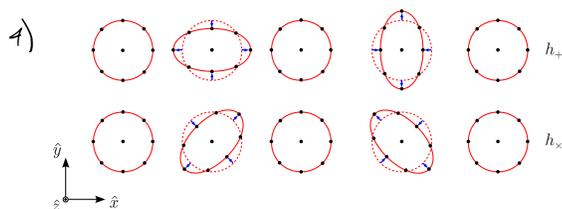
n.B $(0, x_0, 0), (0, -x_0, 0) \Rightarrow \Delta l = L_0 \left[1 - \frac{1}{2} h_{xx} \cos(\omega t) \right]$

Comments :

1) Proper distance do change

2) $\Delta l \propto L_0$ (initial separation) \Rightarrow GW Detectors are large

3) If you rotate the system by $45^\circ \Rightarrow$ Same answer but h_x



Einstein's Quadrupole Formula

We shall describe the generation of gravitational waves by isolated systems.
For each component of $\tilde{h}_{\mu\nu}$ of the perturbation, the linear equation can be solved as:

$$\tilde{h}_{\mu\nu}(t, \vec{x}) = 4G_N \int d^3\vec{x}' \frac{T_{\mu\nu}(t - |\vec{x} - \vec{x}'|, \vec{x}')}{|\vec{x} - \vec{x}'|} \quad \text{in harmonic gauge}$$

- Assume compact source: $|\vec{x} - \vec{x}'| \approx |\vec{x}| \equiv r$

$$\Rightarrow \tilde{h}_{\mu\nu}(t, r) = \frac{4G_N}{r} \int d^3\vec{x}' T^{\mu\nu}(t-r, \vec{x}')$$

- In linearized theory $h_{\mu\nu}$ and $T_{\mu\nu} \rightarrow$ Same order (Must Be). This is telling us that

$$\Rightarrow D_\mu T^{\mu\nu} = 0 \quad \rightarrow \quad \partial_\mu T^{\mu\nu} = 0$$

Starting from this, we can play around with components

$$1. \quad \partial_\mu T^{\mu 0} = 0 \Rightarrow \partial_0 T^{00} = -\partial_K T^{K0}$$

Integrate over region with $T^{\mu\nu} \neq 0$

$$\frac{\partial}{\partial t} \int_V T^{00} d^3\vec{x} = - \int_V \frac{\partial T^{K0}}{\partial x^K} d^3\vec{x} = - \int_\Sigma T^{K0} d\Sigma_K = 0$$

$$\Rightarrow \int_V T^{00} d^3\vec{x} = \text{const} \Rightarrow \tilde{h}^{00} = \text{const} \rightarrow \text{Let's decide to put } \tilde{h}^{00} = 0$$

$$2. \quad \partial_\mu T^{\mu i} = 0 \Rightarrow \partial_0 T^{0i} = -\partial_K T^{Ki} \Rightarrow x^j \partial_0 T^{0i} = -x^j \partial_K T^{Ki}$$

Integrate

$$\begin{aligned} \frac{\partial}{\partial t} \int x^j \partial_0 T^{0i} &= - \int x^j \partial_K T^{Ki} \stackrel{\text{by part}}{=} - \int \frac{\partial}{\partial x^K} (x^j T^{Ki}) d^3\vec{x} + \int T^{Ki} \frac{\partial x^j}{\partial x^K} d^3\vec{x} = \\ &= - \int_\Sigma \underbrace{T^{Ki} x^j}_{=0} d\Sigma_K + \int_V T^{ij} d^3\vec{x} = \int_V T^{ij} d^3\vec{x} \end{aligned}$$

5. Eq. Ten vanish

But $T^{\mu\nu}$ is symmetric \Rightarrow Same result with $i \leftrightarrow j$

$$\text{Add the two} \Rightarrow \frac{\partial}{\partial t} \int_V (T^{i0} x^j + T^{j0} x^i) d^3\vec{x} = 2 \int_V T^{ij} d^3\vec{x} \quad \textcircled{1}$$

$$\textcircled{3) } \partial_\mu T^{\mu 0} = 0 \Rightarrow \partial_0 T^{00} = -\partial_i T^{i0} \Rightarrow x^i x^j \partial_0 T^{00} = x^i x^j \cdot (-\partial_k T^{k0})$$

$$\Rightarrow \int_V x^i x^j \partial_0 T^{00} d^3\vec{x} = -\int_V x^i x^j \partial_k T^{k0} d^3\vec{x} + \int_V \left(T^{k0} \frac{\partial x^i}{\partial x^k} x^j + T^{k0} x^i \frac{\partial x^j}{\partial x^k} \right) d^3\vec{x}$$

$$= \int_V x^i x^j T^{k0} + \int_V (T^{j0} x^i + T^{i0} x^j) d^3\vec{x} = 0$$

$$\Rightarrow \frac{\partial}{\partial t} \int_V x^i x^j \partial_0 T^{00} d^3\vec{x} = \int_V (T^{j0} x^i + T^{i0} x^j) d^3\vec{x}$$

$$\Rightarrow \frac{\partial^2}{\partial t^2} \int_V x^i x^j \partial_0 T^{00} d^3\vec{x} = \frac{\partial}{\partial t} \int_V (T^{j0} x^i + T^{i0} x^j) d^3\vec{x} \Rightarrow$$

$$= 2 \int_V T^{ij} d^3\vec{x} \quad \text{using } \textcircled{1}$$

Definition: Quadrupole moment of source

$$\ddot{Q}^{ij}(t) = \int_V T^{00}(t, \vec{x}) x^i x^j d^3\vec{x} \quad \leadsto \quad \ddot{Q} \equiv \frac{\partial^2 Q}{\partial t^2}$$

Solution For EFE:

$$\tilde{h}_{\mu 0} = 0$$

\leadsto if I have sferic symmetry
g. waves collapse

$$\tilde{h}_{ij} = \frac{2G_N}{r} \ddot{Q}_{ij}(t-r)$$

Move to tt gauge $\left\{ \begin{array}{l} \text{Preserve harmonic} \\ \text{Switches to TT gauge} \end{array} \right.$

- Already $\tilde{h}_{\mu 0} = 0$

- Traceless condition $\delta^{ij} h_{ij}^{\text{TT}} = 0$

- Transverse condition $n^i h_{ij}^{\text{TT}} = 0$ where $\hat{n} = \frac{\vec{x}}{r}$

In order to do that we will introduce some operators

$$P_{ij} \equiv \delta_{ij} - n_i n_j \quad \begin{array}{l} \rightarrow \text{symmetric} \\ \rightarrow \text{Projects vectors on the plane transverse to } \vec{n} \end{array}$$

But $n^i n_i = \delta_{ij} n^i n^j - n_i n_j n^i n^j = n_j n^j - n_j n^j = 0$

• Introduce $P_{ijkl} \equiv P_{ik} P_{jl} - \frac{1}{2} P_{ij} P_{kl}$

$$h_{ij}^{TT} = P_{ijkl} \hat{h}_{kl}$$

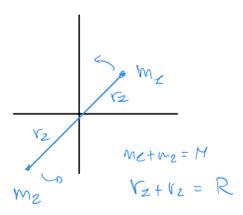
Exercise Prove that h_{ij}^{TT} is traceless ($\delta^{ij} h_{ij}^{TT} = 0$)

• In the end:

$$\begin{cases} h_{\mu\nu}^{TT} = 0 \\ h_{ij}^{TT} = \frac{2G_N}{r} Q_{ij}^{TT} (t-r) \end{cases}$$

Where $Q_{ij}^{TT} = P_{ijkl} A_{kl}$

Binary (S) in orbital orbit



$$\begin{cases} m_1 r_1 + m_2 r_2 = 0 \\ r_1 = \frac{m_2 R}{M} \quad r_2 = \frac{m_1 R}{M} \end{cases}$$

1) Consider newtonian orbit

$$\frac{G_N m_1 m_2}{R^2} = m_1 \omega^2 \quad r_1 = \frac{m_2 m_2 R}{M} \omega^2 \Rightarrow \omega^2 = \sqrt{\frac{G_N M^3}{R^3}}$$

2) Trajectories

$$\vec{x}_1 = \begin{pmatrix} r_1 \cos \omega t \\ r_1 \sin \omega t \\ 0 \end{pmatrix} \quad \vec{x}_2 = \begin{pmatrix} -r_2 \cos \omega t \\ -r_2 \sin \omega t \\ 0 \end{pmatrix}$$

$$\begin{aligned} T^{00} &= \sum_{i=1}^2 m_i c^2 \delta(x-x_i) \delta(y-y_i) \delta(z) \\ &\Rightarrow Q^{ij}(t) = \int_V T^{00}(t, \vec{x}) x^i x^j d^3x \end{aligned}$$

$$\begin{aligned} S_0 \quad Q_{xx} &= \sum_{i=1}^2 \int m_i c^2 \delta(x-x_i) \delta(y-y_i) \delta(z) x^2 dx dy dz \\ &= m_1 x_1^2(t) + m_2 x_2^2(t) = \frac{MR^2}{2} \cos^2 \omega t + \text{const} \end{aligned}$$

where $\mu = \frac{m_1 m_2}{m_1 + m_2}$

In the end

$$Q_{ij} = \frac{MR^2}{2} \begin{pmatrix} \cos(2\omega t) & \sin(2\omega t) & 0 \\ \sin(2\omega t) & -\cos(2\omega t) & 0 \\ 0 & 0 & 0 \end{pmatrix} (+ \text{const})$$

- Assuming observer along z-axis
- Unit vector (0,0,1)
- Projection $P_{ij} = \delta_{ij} - n_i n_j = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

$$Q_{xx}^{\text{TT}} = P_{xxij} Q^{ij} = \left(P_{xi} P_{xj} - \frac{1}{2} P_{xx} P_{ij} \right) Q^{ij}$$

$$= \left(P_{xx}^2 - \frac{1}{2} P_{xx}^2 \right) Q_{xx} - \frac{1}{2} P_{xx} P_{xy} Q_{xy} - \frac{1}{2} (Q_{xx} - Q_{yy})$$

Then

$$Q_{ij}^{\text{TT}} = \begin{pmatrix} \frac{1}{2}(Q_{xx} - Q_{yy}) & Q_{xy} & 0 \\ Q_{xy} & -\frac{1}{2}(Q_{xx} - Q_{yy}) & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

So $h_{\mu 0}^{\text{TT}} = 0$

$$h_{ij}^{\text{TT}} = \frac{2G_N}{r} \ddot{Q}_{ij}^{\text{TT}}(t-r) \Rightarrow h_{\mu\nu}^{\text{TT}} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & h_+ & h_x & 0 \\ 0 & h_x & -h_+ & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$h_+(t) = -\frac{4G_N M R^2 \omega^2}{c^4 z} \cos \left[2\omega \left(t - \frac{z}{c} \right) \right]$$

$$h_x(t) = -\frac{4G_N M R^2 \omega^2}{c^4 z} \sin \left[2\omega \left(t - \frac{z}{c} \right) \right]$$

Comparison with EM